

# JX

## Compact & Complete

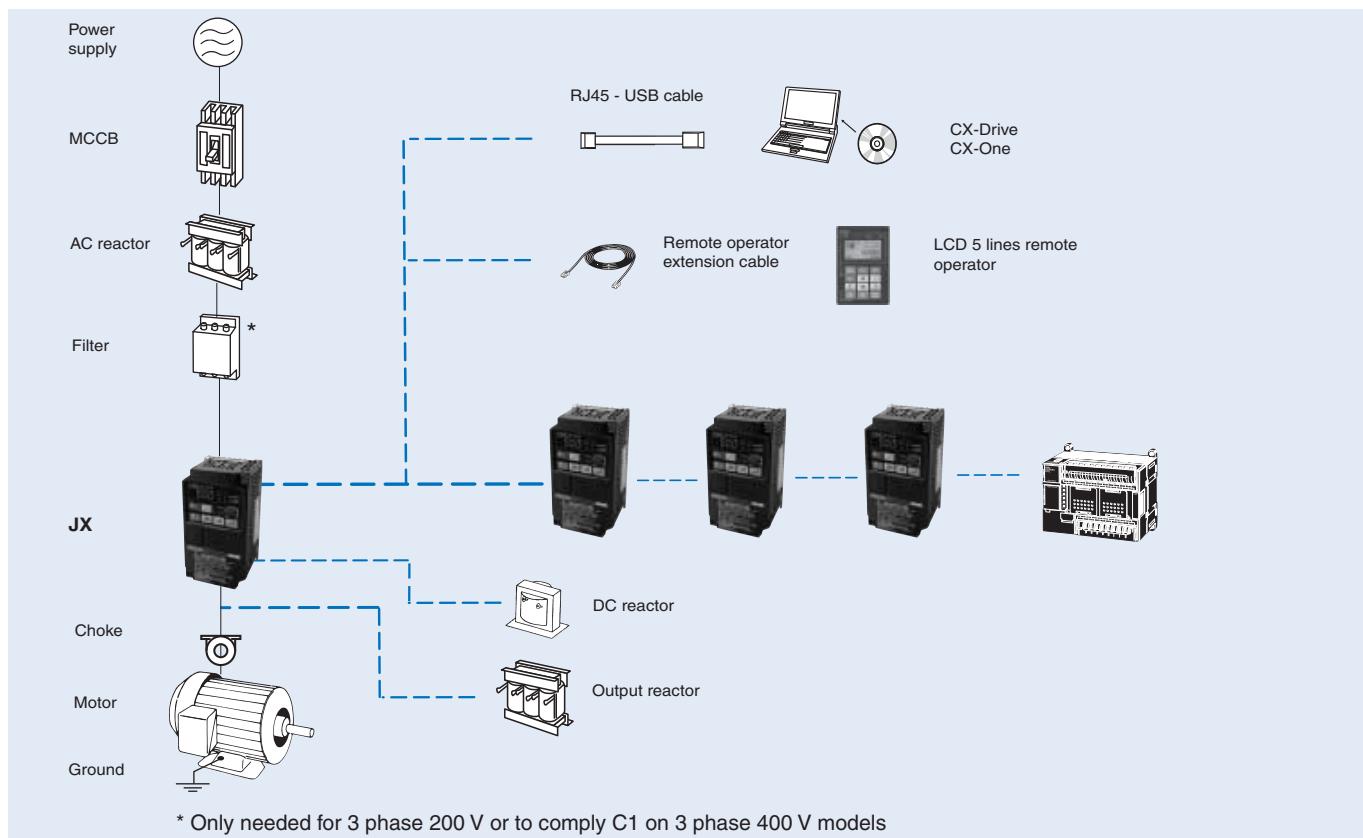
- V/f controlled inverter
- Side by side mounting
- Built-in EMC filter
- Built-in RS-485 Modbus
- Overload detection function (150% during 60s)
- PID
- Micro-surge voltage suppression
- Automatic energy saving
- Emergency shut-off
- Second motor setting
- Auto carrier-frequency reduction
- PTC thermistor input
- Cooling fan switch control
- PC configuration tool: CX-Drive
- CE, UL, cUL, RoHS

## Ratings

- 200 V Class single-phase 0.2 to 2.2 kW
- 200 V Class three-phase 0.2 to 7.5 kW
- 400 V Class three-phase 0.4 to 7.5 kW

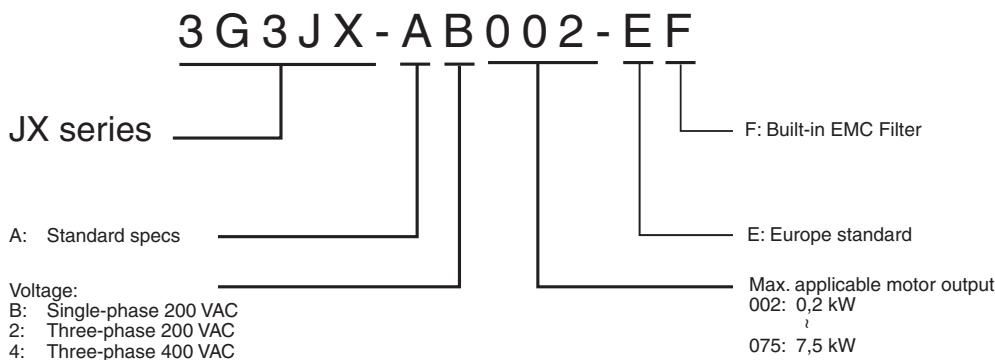


## System configuration



## Specifications

## Type designation



## 200 V class

Single-phase: 3G3JX□		AB002	AB004	AB007	AB015	AB022	-	-	-
Three-phase: 3G3JX□		A2002	A2004	A2007	A2015	A2022	A2037	A2055	A2075
Motor kW <sup>1</sup>	Applicable motor capacity	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5
Output characteristics	Inverter capacity kVA	200 V	0.4	0.9	1.3	2.4	3.4	5.5	8.3
		240 V	0.5	1.0	1.6	2.9	4.1	6.6	9.9
Power supply	Rated output current (A)	1.4	2.6	4.0	7.1	10.0	15.9	24.0	32.0
	Max. output voltage	Proportional to input voltage: 0...240 V							
Max. output frequency		400 Hz							
Rated input voltage and frequency		Single-phase 200...240 V 50/60 Hz 3-phase 200...240 V 50/60 Hz							
Rated input current (A) Three-phase 200 V		1.8	3.4	5.2	9.3	13.0	20.0	30.0	40.0
Rated input current (A) Single-phase 200 V		3.1	5.8	9.0	16.0	22.5	-	-	-
Allowable voltage fluctuation		-15%...+10%							
Allowable frequency fluctuation		+5%							
Built-in filter		EMC filter (C1 single phase)							
Braking torque		At short-time deceleration At capacitor feedback	Approx. 50%		50% for 3-phase 20 to 40% for 1-phase	Approx 20% to 40%		Approx 20%	
Cooling method		Self cooling		Forced-air-cooling					

\*1 Based on a standard 3-Phase standard motor.

## 400 V class

Three-phase: 3G3JX□		A4004	A4007	A4015	A4022	A4040	A4055	A4075	
Motor kW <sup>1</sup>	Applicable motor capacity	0.4	0.75	1.5	2.2	4.0	5.5	7.5	
Output characteristics	Inverter capacity kVA	380 V	0.9	1.6	2.5	3.6	5.6	8.5	
		480 V	1.2	2.0	3.1	4.5	7.1	10.8	
Rated output current (A)		1.5	2.5	3.8	5.5	8.6	13.0	16.0	
Max. output voltage		Proportional to input voltage: 0...480 V							
Max. output frequency		400 Hz							
Rated input voltage and frequency		3-phase 380...480 V 50/60 Hz							
Rated input current (A)		2.0	3.3	5.0	7.0	11.0	16.5	20.0	
Allowable voltage fluctuation		-15%...+10%							
Allowable frequency fluctuation		+5%							
Built-in filter		EMC filter C2 class							
Braking torque		At short-time deceleration At capacitor feedback	Approx. 50%		Approx. 20% to 40%			Approx. 20%	
Cooling method		Self cooling		Forced-air-cooling					

\*1 Based on a standard 3-Phase standard motor.

## Specifications

### Common specifications

Model number 3G3JX□		Specifications
Control functions	<b>Control methods</b>	Phase-to-phase sinusoidal modulation PWM (V/f)
	<b>Output frequency range</b>	0.5..400 Hz
	<b>Frequency precision</b>	Digital set value: $\pm 0.01\%$ of the max. frequency Analogue set value: $\pm 0.4\%$ of the max. frequency ( $25 \pm 10^\circ\text{C}$ )
	<b>Resolution of frequency set value</b>	Digital set value: 0.1 Hz Analogue set value: 1/1000 of maximum frequency
	<b>Resolution of output frequency</b>	0.1 Hz
	<b>Overload capability</b>	150% rated output current for one minute
	<b>Frequency set value</b>	0 to 10 VDC (10 k $\Omega$ ), 4 to 20 mA (250 $\Omega$ ), frequency setting volume (selectable), RS485 Modbus
Functionality	<b>V/f Characteristics</b>	Constant/ reduced torque
	<b>Inputs signals</b>	FW (forward), RV (reverse), CF1 to CF4 (multi-step speed), JG (jogging), DB (external DC injection braking), SET (2nd function), 2CH (2-step acceleration/deceleration), FRS (free run), EXT (external trip), USP (USP function), SFT (soft lock), AT (analog current input function selection), RS (reset), PTC (thermistor input), STA (3-wire startup), STP (3-wire stop), F/R (3-wire forward/reverse), PID (PID selection), PIDC (PID integral reset), UP (UP of UP/DWN function), DWN (DWN of UP/DWN function), UDC (data clear of UP/DWN function), OPE (forced OPE mode), ADD (frequency addition), F-TM (forced terminal block), RDY (operation ready), SP-SET (special setting), EMR (emergency shutdown)
	<b>Output signals</b>	RUN (signal during operation), FA1 (frequency arrival signal 1), FA2 (frequency arrival signal 2), OL (overload warning signal), OD (PID excess deviation signal), AL (alarm signal), DC (analog input disconnection detection signal), FBV (PID FB status output), NDc (network error), LOG (logical operation result), ODc (communication option disconnected), LOC (light load signal)
	<b>Standard functions</b>	AVR function, V/f characteristic selection, upper/lower limit, 16-step speeds, starting frequency adjustment, jogging operation, carrier frequency adjustment, PID control, frequency jump, analog gain/bias adjustment, S-shape acceleration/deceleration, electronic thermal characteristics/level adjustment, retry function, simplified torque boost, trip monitor, soft lock function, frequency conversion display, USP function, 2nd control function, motor rotation speed UP/DOWN, overcurrent suppression function
	<b>Analogue inputs</b>	2 analogue inputs 0 to 10 V (20 k $\Omega$ ), 4 to 20 mA (250 $\Omega$ )
	<b>Accel/Decel times</b>	0.01 to 3000 s (line/curve selection), 2nd accel/decel setting available
	<b>Display</b>	Status indicator LED's Run, Program, Power, Alarm, Power, Hz, Amps, Volume Led indicator Digital operator: Available to monitor frequency reference, output current, output frequency
Protection functions	<b>Motor overload protection</b>	Electronic Thermal overload relay and PTC thermistor input
	<b>Instantaneous overcurrent</b>	180% of rated current
	<b>Overload</b>	150% for 1 minute
	<b>Overspeed</b>	790 V for 400 V type and 395 for 200 V type
	<b>Momentary power loss</b>	Following items are selectable: Alarm, 0 Hz start, frequency output at interruption, maximum frequency
	<b>Cooling fin overheating</b>	Temperature monitor and error detection
	<b>Stall prevention level</b>	Selectable level applicable only at constant speed or during acceleration and constant speed
Ambient conditions	<b>Ground fault</b>	Detected at power-on
	<b>Power charge indication</b>	On when power is supplied to the control part
	<b>Degree of protection</b>	IP20
	<b>Ambient humidity</b>	90% RH or less (without condensation)
	<b>Storage temperature</b>	-20°C..+65 °C (short-term temperature during transportation)
	<b>Ambient temperature</b>	-10°C to 50°C (Both the carrier frequency and output current need to be reduced at over 40°C.)
	<b>Installation</b>	Indoor (no corrosive gas, dust, etc.)
<b>Installation height</b>		Max. 1000 m
<b>Vibration</b>		5.9 m/s <sup>2</sup> (0.6 G), 10 to 55 Hz (Complies with the test method specified in JIS C0040 (1999).)

## Dimensions

IP 20 type 0.2 to 7.5 kW

Figure 1

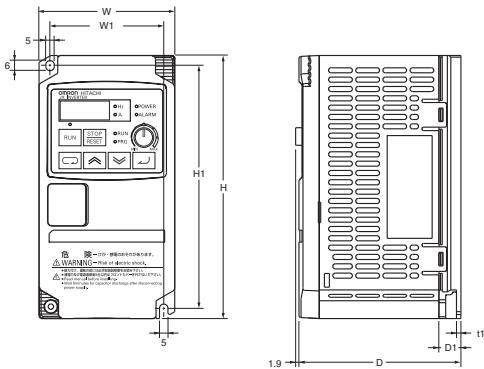
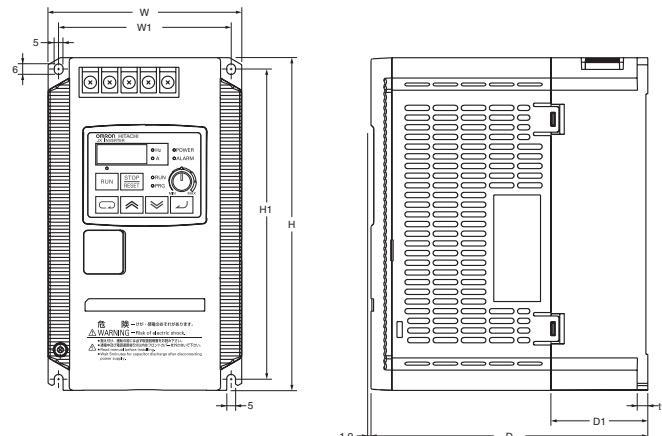


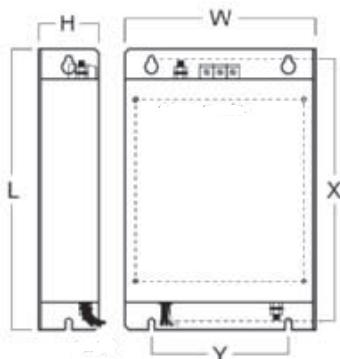
Figure 2



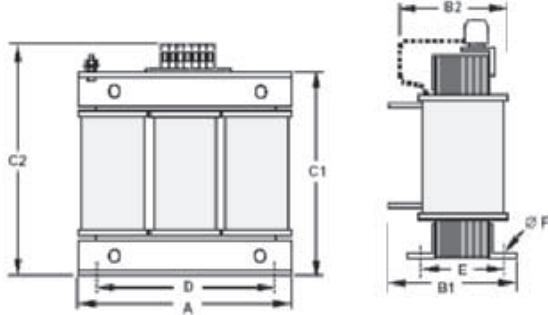
Voltage class	Max. applicable motor output kW	Inverter model 3G3JX□	Figure	Dimensions in mm							
				W1	H1	W	H	D	t1	D1	Weight
Single-phase 200 V	0.2	AB002	1	67	143	80	155	95.5	2.6	13	0.8
	0.4	AB004	1					109.5		27	0.9
	0.75	AB007	2					130.5		28	1.5
	1.5	AB015	2					189	6	55	2.3
	2.2	AB022	2					157.5		55	2.4
Three-phase 200 V	0.2	A2002	1	67	143	80	155	95.5	2.6	13	0.8
	0.4	A2004	1					109.5		27	0.9
	0.75	A2007	1					132.5		50	1.1
	1.5	A2015	2	98	176	110	189	157.5	6	55	2.2
	2.2	A2022	2					189		55	2.4
	3.7	A2037	2					164	1.6	77.5	4.2
	5.5	A2055	2					235		77.5	4.2
	7.5	A2075	2					180		130.5	2.6
Three-phase 400 V	0.4	A4004	2	98	176	110	189	109.5	2.6	28	1.5
	0.75	A4007	2					130.5		28	2.3
	1.5	A4015	2					157.5		55	2.4
	2.2	A4022	2					164	1.6	77.5	4.2
	4.0	A4040	2					235		77.5	4.2
	5.5	A4055	2					180		130.5	2.6
	7.5	A4075	2					250		109.5	2.6

## Rasmi footprint Filters

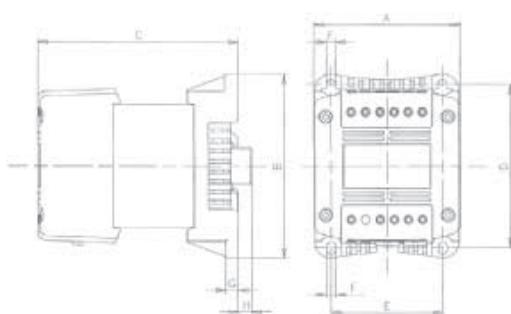
Filter only needed by the 1-phase 200 V or 3-phase 400 V to comply with C1 EMC class.



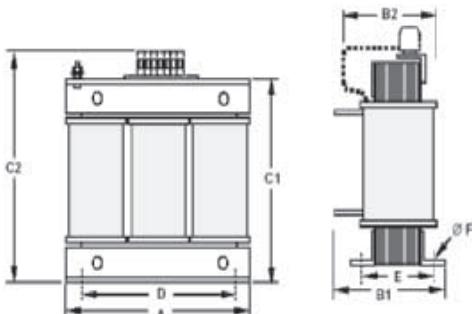
Rasmi model	Dimensions						Weight kg	
	W	H	L	X	Y	M		
1x200 V	AX-FIJ1006-RE	81	40	193	183	57	M4	0.5
	AX-FIJ1010-RE	112	47	226	216	88	M4	0.6
	AX-FIJ1026-RE	112	47	226	216	88	M4	0.8
3x200 V	AX-FIJ2006-RE	81	50	193	183	57	M4	1.0
	AX-FIJ2020-RE	112	50	226	216	88	M4	1.3
	AX-FIJ2040-RE	182	55	289	279	150	M5	2.3
3x400 V	AX-FIJ3005-RE	112	45	226	216	88	M4	0.9
	AX-FIJ3011-RE	112	45	226	216	88	M4	1.1
	AX-FIJ3020-RE	182	45	289	279	150	M4	1.7

**Input AC Reactor**

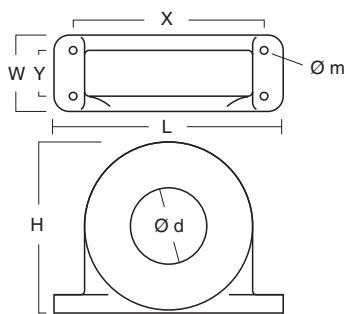
Voltage	Reference	Dimensions						Weight kg
		A	B2	C2	D	E	F	
200 V	AX-RAI02800080-DE	120	70	120	80	52	5.5	1.78
	AX-RAI00880175-DE	120	80	120	80	62	5.5	2.35
	AX-RAI00350335-DE	180	85	190	140	55	6	5.5
400 V	AX-RAI07700042-DE	120	70	120	80	52	5.5	1.78
	AX-RAI03500090-DE	120	80	120	80	62	5.5	2.35
	AX-RAI01300170-DE	120	80	120	80	62	5.5	2.50

**DC Reactor**

Voltage	Reference	Dimensions								Weight kg	
		A	B	C	D	E	F	G	H		
200 V	AX-RC21400016-DE	84	113	96	101	66	5	7.5	2	1.22	
	AX-RC10700032-DE			105						1.60	
	AX-RC06750061-DE			116						1.95	
	AX-RC03510093-DE	108	135	124	120	82	6.5	9.5	3.20		
	AX-RC02510138-DE	120	152	136	135	94	7		5.20		
	AX-RC01600223-DE			146					-	6.00	
400 V	AX-RC43000020-DE	84	113	96	101	66	5	7.5	2	1.22	
	AX-RC27000030-DE			105						1.60	
	AX-RC14000047-DE			116						1.95	
	AX-RC10100069-DE	108	135	133	120	82	6.5	9.5	3.70		
	AX-RC06400116-DE	120	152	136	135	94	7		5.20		
	AX-RC04410167-DE			146					-	6.00	

**Output AC Reactor**

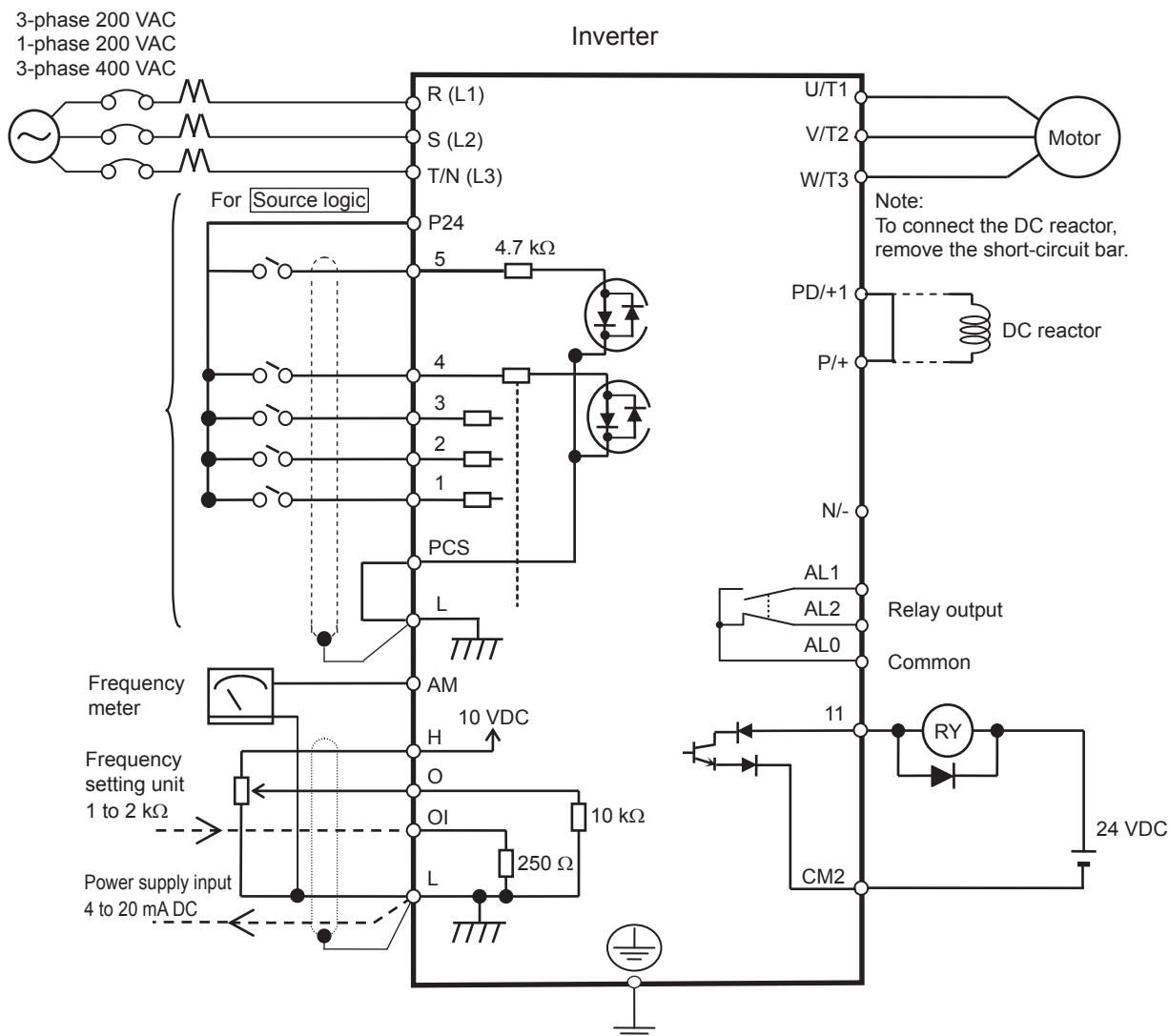
Voltage	Reference	Dimensions						Weight kg
		A	B2	C2	D	E	F	
200 V	AX-RAO11500026-DE	120	70	120	80	52	5.5	1.78
	AX-RAO07600042-DE	120	70	120	80	52	5.5	1.78
	AX-RAO04100075-DE	120	80	120	80	62	5.5	2.35
	AX-RAO03000105-DE	120	80	120	80	62	5.5	2.35
	AX-RAO01830180-DE	180	85	190	140	55	6	5.5
	AX-RAO01150220-DE	180	85	190	140	55	6	5.5
	AX-RAO00950320-DE	180	85	205	140	55	6	6.5
400 V	AX-RAO16300038-DE	120	70	120	80	52	5.5	1.78
	AX-RAO11800053-DE	120	80	120	80	52	5.5	2.35
	AX-RAO07300080-DE	120	80	120	80	62	5.5	2.35
	AX-RAO04600110-DE	180	85	190	140	55	6	5.5
	AX-RAO03600160-DE	180	85	205	140	55	6	6.5

**Chokes**

Reference	D diameter	Motor KW	Dimensions						Weight kg
			L	W	H	X	Y	m	
AX-FER2102-RE	21	< 2.2	85	22	46	70	-	5	0.1
AX-FER2515-RE	25	< 15	105	25	62	90	-	5	0.2

## Installation

## Standard connections



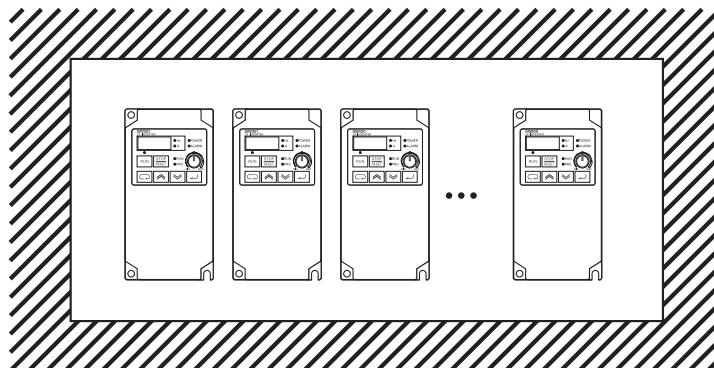
## Terminal Block Specifications

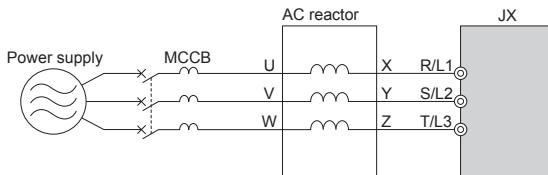
Terminal	Name	Function (signal level)
R/L1, S/L2, T/N/L3	Main circuit power supply input	Used to connect line power to the drive. Drives with single-phase 200 V input power use only terminals R/L1 and N (T/L3), terminal S/L2 is not available for these units
U/T1, V/T2, W/T3	Inverter output	Used to connect the motor
PD/+1, P/+	External DC reactor terminal	Normally connected by the short-circuit bar. Remove the short-circuit bar between +1 and P/+2 when a DC reactor is connected.
P/+, N/-	Regenerative braking unit connection terminal	Connect optional regenerative braking units (If a braking torque is required)
⊕	Grounding	For grounding (grounding should conform to the local grounding code.)

## Control Circuit

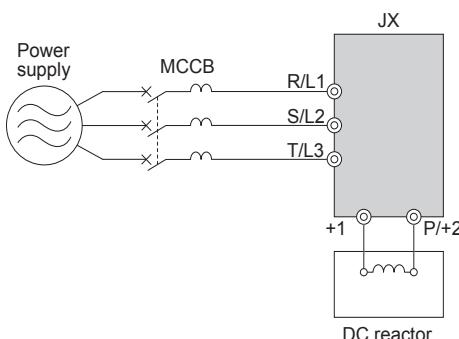
Type	No.	Signal name	Function	Signal level
Digital input signals	PCS	Input power supply	External power supply terminal for input signal (input) ...At sink logic Internal power supply output terminal for input signal (output) ...At source logic	24 VDC ±10%
	P24	Internal 24 VDC	24 VDC internal power supply	24 VDC±10% 100 mA
	1	Multi-function Input selection 1	Factory setting: Forward/ Stop	
	2	Multi-function Input selection 2	Factory setting: Reverse/ Stop	
	3	Multi-function Input selection 3	Factory setting: Fault reset	
	4	Multi-function Input selection 4	Factory setting: Emergency stop fault	
	5	Multi-function Input selection 5	Factory setting: Multi-step speed reference 1	
Analog input signal	L	Multi-function Input selection common	--	--
	H	Frequency reference power supply	10 VDC 10 mA max	
	O	Voltage frequency reference signal	0 to 10 VDC (10 kΩ)	
	OI	Current frequency reference signal	4 to 20 mA (250 Ω)	
Digital output signals	L	Frequency reference common	--	
	AL2	NC output	Factory default relay settings Under normal operation: AL2-AL0 Closed Under abnormal operation or power shutdown: AL1-AL0 Open	250 VAC 2.5 A 30 VDC 3 A
	AL1	NO output		250 VAC 1 A 30 VDC 1 A
	AL0	Relay Output common		
	11	Multi-function output terminal	Factory setting: Frequency arrival signal at a constant speed	27 VDC 50 mA max
Monitor Signal	CM2	Output signal common	--	
	AM	Analog frequency monitor/Analog output current monitor	Factory setting: Analog frequency monitor	0 to 10 VDC 1 mA

### Side by side mounting



**Input AC Reactor**

3 phase 200 V class				400 V class			
Max. applicable motor output kW	Reference	Current value A	Inductance mH	Max. applicable motor output kW	Reference	Current value A	Inductance mH
0.1 to 1.5	AX-RAI02800080-DE	8.0	2.8	0.4 to 1.5	AX-RAI07700042-DE	4.2	7.7
2.2 to 3.7	AX-RAI00880175-DE	17.5	0.88	2.2 to 4.0	AX-RAI03500090-DE	9.0	3.5
5.5 to 7.5	AX-RAI00350335-DE	33.5	0.35	5.5 to 7.5	AX-RAI01300170-DE	17.0	1.3

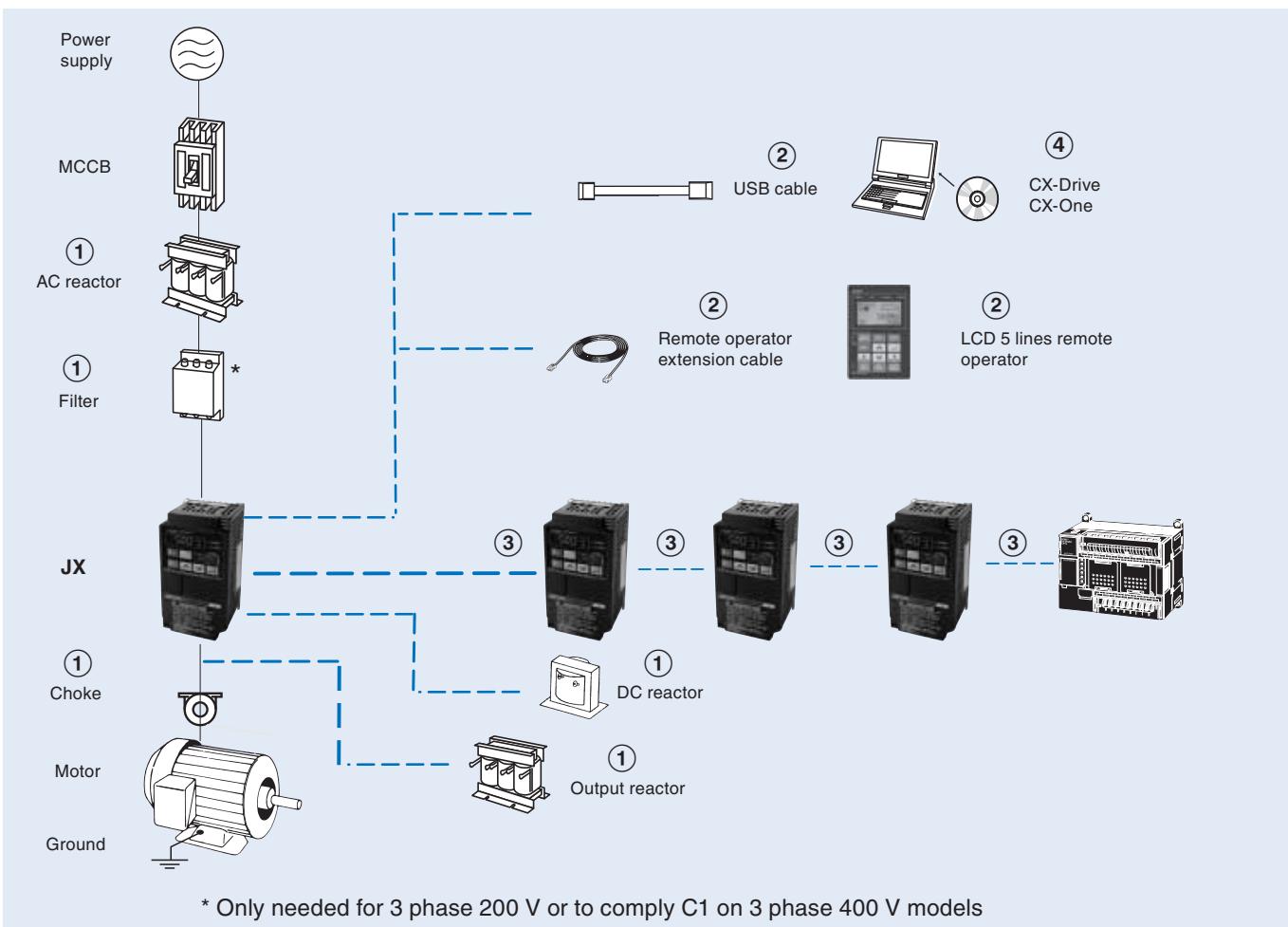
**DC Reactor**

200 V class				400 V class			
Max. applicable motor output kW	Reference	Current value A	Inductance mH	Max. applicable motor output kW	Reference	Current value A	Inductance mH
0.2	AX-RC21400016-DE	1.6	21.4	-	-	-	-
0.4	AX-RC10700032-DE	3.2	10.7	0.4	AX-RC43000020-DE	2.0	43.0
0.7	AX-RC06750061-DE	6.1	6.75	0.7	AX-RC27000030-DE	3.0	27.0
1.5	AX-RC03510093-DE	9.3	3.51	1.5	AX-RC14000047-DE	4.7	14.0
2.2	AX-RC02510138-DE	13.8	2.51	2.2	AX-RC10100069-DE	6.9	10.1
3.7	AX-RC01600223-DE	22.3	1.60	4.0	AX-RC06400116-DE	11.6	6.40
5.5	AX-RC01110309-DE	30.9	1.11	5.5	AX-RC04410167-DE	16.7	4.41
7.5	AX-RC00840437-DE	43.7	0.84	7.5	AX-RC03350219-DE	21.9	3.35

**Output AC Reactor**

200 V class				400 V class			
Max. applicable motor output kW	Reference	Current value A	Inductance mH	Max. applicable motor output kW	Reference	Current value A	Inductance mH
0.1 to 0.4	AX-RAO11500026-DE	2.6	11.50	0.4 to 1.5	AX-RAO16300038-DE	3.8	16.30
0.75	AX-RAO07600042-DE	4.2	7.60	2.2	AX-RAO11800053-DE	5.3	11.80
1.5	AX-RAO04100075-DE	7.5	4.10	4.0	AX-RAO07300080-DE	8.0	7.30
2.2	AX-RAO03000105-DE	10.5	3.00	5.5	AX-RAO04600110-DE	11.0	4.60
3.7	AX-RAO01830160-DE	16.0	1.83	7.5	AX-RAO03600160-DE	16.0	3.60
5.5	AX-RAO01150220-DE	22.0	1.15	-	-	-	-
7.5	AX-RAO00950320-DE	32.0	0.95	-	-	-	-

## Ordering information



### 3G3JX

Specifications			Model
Voltage class	Max. applicable motor output kW	Rated output current (A)	Standard
Single-phase 200 V	0.2	1.4	3G3JX-AB002-EF
	0.4	2.6	3G3JX-AB004-EF
	0.75	4	3G3JX-AB007-EF
	1.5	7.1	3G3JX-AB015-EF
	2.2	10	3G3JX-AB022-EF
Three-phase 200 V	0.2	1.4	3G3JX-A2002-E
	0.4	2.6	3G3JX-A2004-E
	0.75	4	3G3JX-A2007-E
	1.5	7.1	3G3JX-A2015-E
	2.2	10	3G3JX-A2022-E
	3.7	15.9	3G3JX-A2037-E
	5.5	24	3G3JX-A2055-E
Three-phase 400 V	0.4	1.5	3G3JX-A4004-EF
	0.75	2.5	3G3JX-A4007-EF
	1.5	3.8	3G3JX-A4015-EF
	2.2	5.5	3G3JX-A4022-EF
	4.0	8.6	3G3JX-A4040-EF
	5.5	13	3G3JXA4055-EF
	7.5	16	3G3JXA4075-EF

## ① Line filters

Inverter		Line filter Rasmi		
Voltage	Model 3G3JX-□	Reference	Rated current (A)	Weight (kg)
1-Phase 200 VAC	AB002 / AB004	AX-FIJ1006-RE	6	0.5
	AB007	AX-FIJ1010-RE	10	0.6
	AB015 / AB022	AX-FIJ1026-RE	26	0.8
3-Phase 200 VAC	A2002 / A2004 / A2007	AX-FIJ2006-RE	6	1.0
	A2015 / A2022 / A2037	AX-FIJ2020-RE	20	1.3
	A2055 / A2075	AX-FIJ2040-RE	40	2.3
3-Phase 400 VAC	A4004 / A4007 / A4015	AX-FIJ3005-RE	5	0.9
	A4022 / A4040	AX-FIJ3011-RE	11	1.1
	A4055 / A4075	AX-FIJ3020-RE	20	1.7

## ① Input AC Reactors

Inverter		AC Reactor
Voltage	Model 3G3JX-□	Reference
3-Phase 200 VAC	A2002 / A2004 / A2007	AX-RAI02800080-DE
	A2015 / A2022 / A2037	AX-RAI00880175-DE
	A2055 / A2075	AX-RAI00350335-DE
1-Phase 200 VAC	AB002 / AB004	Under development
	AB007	
	AB015 / AB022	
3-Phase 400 VAC	A4004 / A4007 / A4015	AX-RAI07700042-DE
	A4022 / A4040	AX-RAI03500090-DE
	A4055 / A4075	AX-RAI01300170-DE

## ① DC Reactors

200V single phase		200V 3-phase		400V 3-phase	
Inverter	DC Reactor	Inverter	DC Reactor	Inverter	DC Reactor
3G3JX-AB002	AX-RC10700032-DE	3G3JX-A2002	AX-RC21400016-DE	-	-
3G3JX-AB004	AX-RC06750061-DE	3G3JX-A2004	AX-RC10700032-DE	3G3JX-A4004	AX-RC43000020-DE
3G3JX-AB007	AX-RC03510093-DE	3G3JX-A2007	AX-RC06750061-DE	3G3JX-A4007	AX-RC27000030-DE
3G3JX-AB015	AX-RC02510138-DE	3G3JX-A2015	AX-RC03510093-DE	3G3JX-A4015	AX-RC14000047-DE
3G3JX-AB022	AX-RC01600223-DE	3G3JX-A2022	AX-RC02510138-DE	3G3JX-A4022	AX-RC10100069-DE
-		3G3JX-A2037	AX-RC01600223-DE	3G3JX-A4040	AX-RC06400116-DE
-		3G3JX-A2055	AX-RC01110309-DE	3G3JX-A4055	AX-RC04410167-DE
-		3G3JX-A2075	AX-RC00840437-DE	3G3JX-A4075	AX-RC03350219-DE

## ① Chokes

Model	Diameter	Description
AX-FER2102-RE	21	For 2.2 KW motors or below
AX-FER2515-RE	25	For 7.5 KW motors or below

## ① Output AC Reactors

Inverter		AC Reactor
Voltage	Model 3G3JX-□	Reference
200 VAC	A2001 / A2002 / A2004 AB001 / AB002 / AB004	AX-RAO11500026-DE
	A2007/AB007	AX-RAO07600042-DE
	A2015 / AB015	AX-RAO04100075-DE
	A2022 / AB022	AX-RAO03000105-DE
	A2037	AX-RAO01830160-DE
	A2055	AX-RAO01150220-DE
	A2075	AX-RAO00950320-DE
400 VAC	A4004 / A4007 / A4015	AX-RAO16300038-DE
	A4022	AX-RAO11800053-DE
	A4040	AX-RAO07300080-DE
	A4055	AX-RAO04600110-DE
	A4075	AX-RAO03600160-DE

## ② Accessories

Types	Model	Description	Functions
Digital operator	AX-OP05-E	LCD remote operator	5 Line LCD remote operator with copy function, cable length max. 3m. *1
	3G3AX-CAJOP300-EE	Remote operator cable	3 meters cable for connecting remote operator
	3G3AX-OP01	LED remote operator	LED remote operator, cable length max. 3m
	4X-KITMINI	Mounting kit for LED operator	Mounting kit for LED operator on panel
Accessories	3G3AX-PCACN2	USB converter / USB cable	RJ45 to USB connection cable
	3G3AX-CTB020-EE	RJ45 T-Branch cable	T cable for RS-422 connection
	3G3AX-CTR150-EE	RJ45 Terminator resistor	Terminator resistor for RS-422 connection

\*1 Please note, for 3G3JX inverters models, the operator will only display 2 lines of text.

## ④ Computer software

Types	Model	Description	Installation
Software	CX-Drive	Computer software	Configuration and monitoring software tool
	CX-One	Computer software	Configuration and monitoring software tool
	€Saver	Computer software	Software tool for Energy Saving calculation

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.