

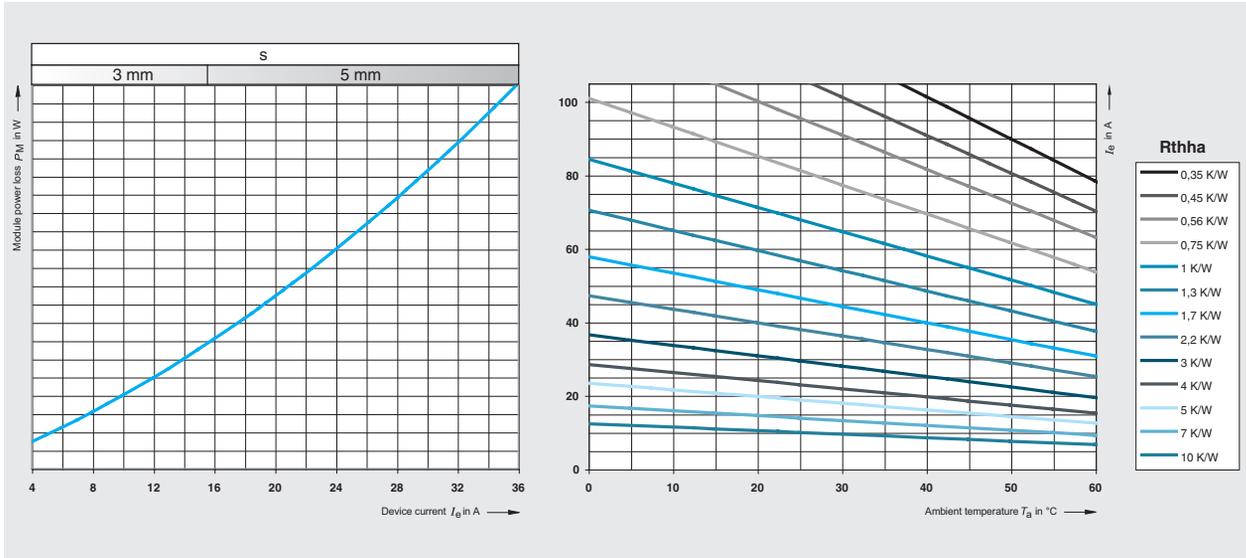
# Controls — Solid-State Switching Devices

## Solid-State Relays

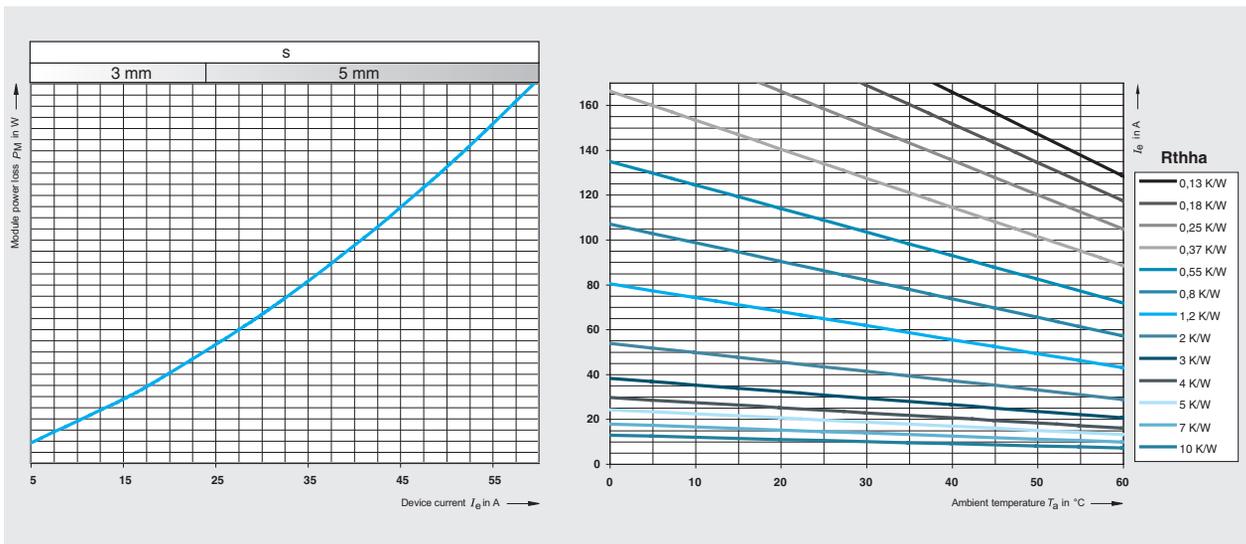
### 3RF22 solid-state relays, 3-phase, 45 mm

#### Characteristic curves

Dependence of the device current  $I_e$  on the ambient temperature  $T_a$  (two-phase controlled)



Type current 30 A (3RF22 30-.AB..)



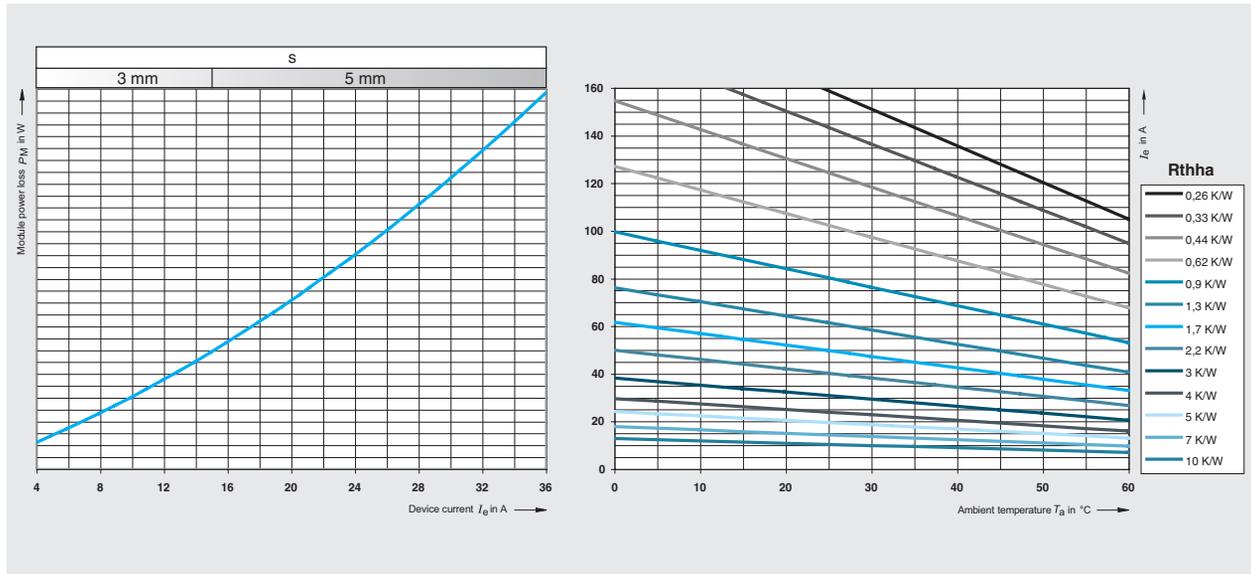
Type current 55 A (3RF22 55-.AB..)

# Controls — Solid-State Switching Devices

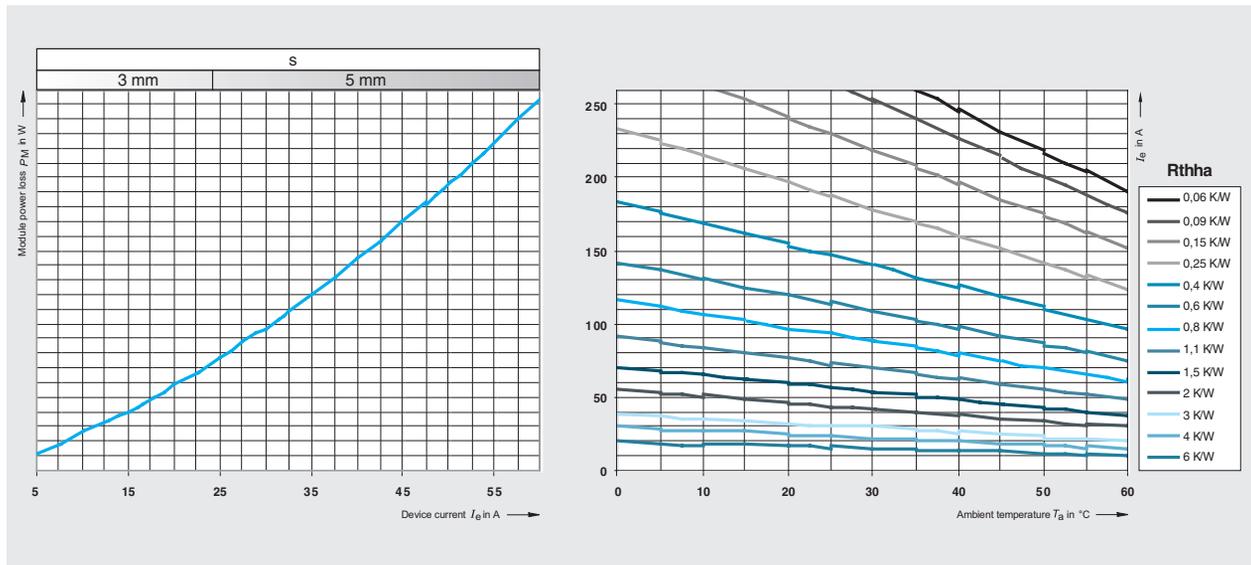
## Solid-State Relays

3RF22 solid-state relays, 3-phase, 45 mm

Dependence of the device current  $I_e$  on the ambient temperature  $T_a$  (three-phase controlled)



Type current 30 A (3RF22 30-.AC..)



Type current 55 A (3RF22 55-.AC..)

Arrangement example

Given conditions:  $I_e = 55$  A and  $T_a = 40$  C.

The task is to find the thermal resistance  $R_{thha}$  and the heat sink overtemperature  $dT_{ha}$ .

From the diagram on the left  $\rightarrow P_M = 227$  W,  
from the diagram on the right  $\rightarrow R_{thha} = 0.09$  K/W.

This results in:

$$dT_{ha} = R_{thha} \times PM = 0.09 \text{ K/W} \times 227 \text{ W} = 20.4 \text{ K.}$$

At  $dT_{ha} = 20.4$  K the heat sink must therefore have an  $R_{thha} = 0.09$  K/W.

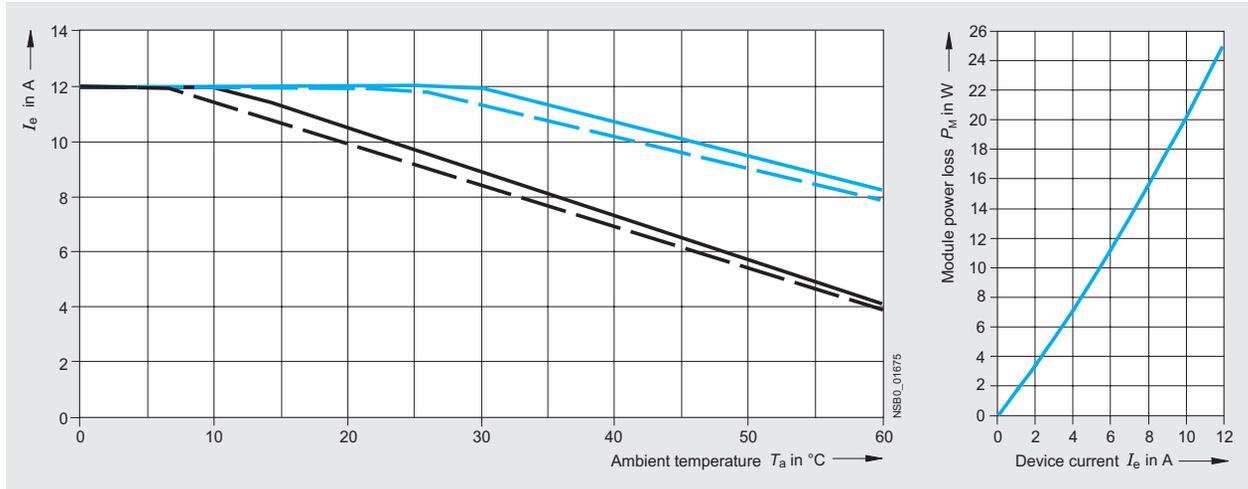
# Controls — Solid-State Switching Devices

## Solid-State Contactors

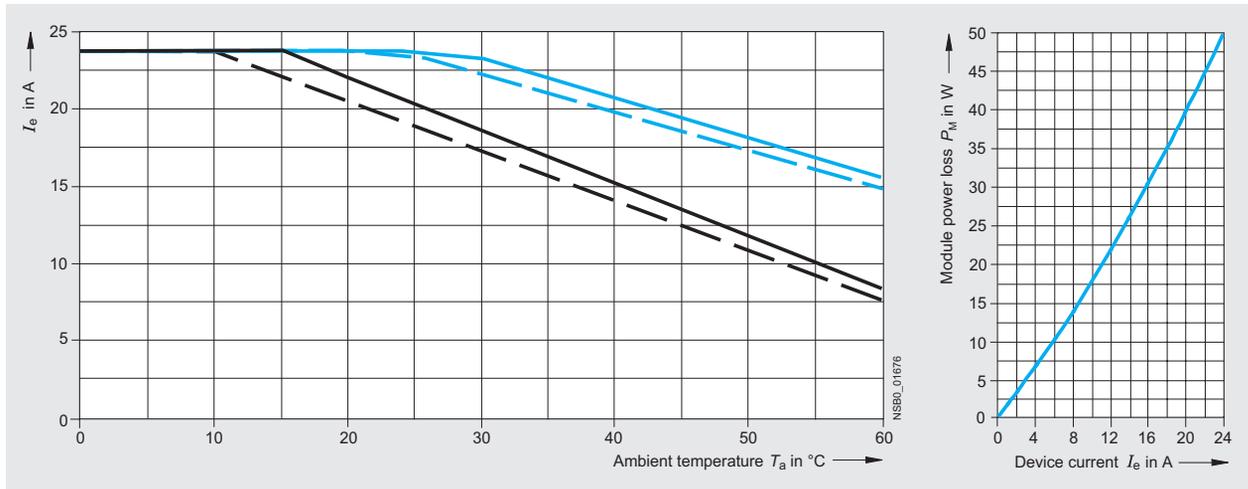
### 3RF24 solid-state contactors, 3-phase

#### Characteristic curves

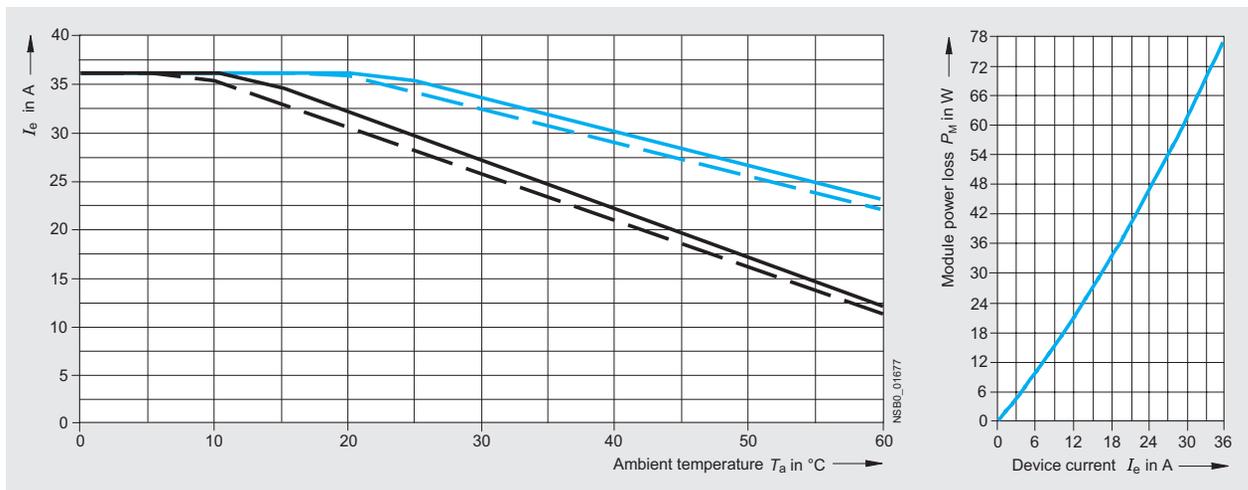
##### Derating curves, two-phase controlled



Type current 10.5 A (3RF24 10-AB..)



Type current 20 A (3RF24 20-AB..)



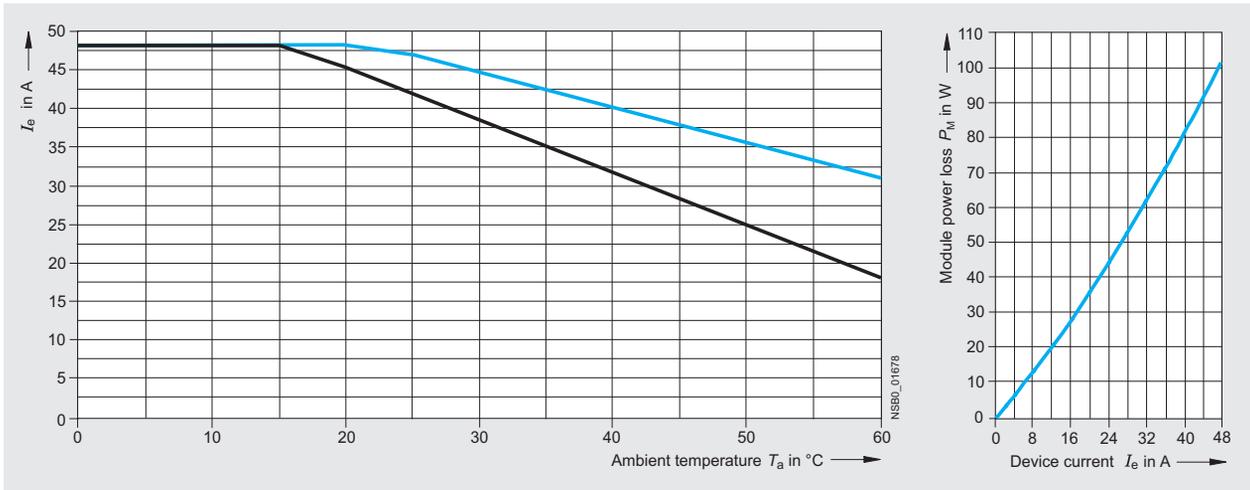
Type current 30 A (3RF24 30-AB..)

# Controls — Solid-State Switching Devices

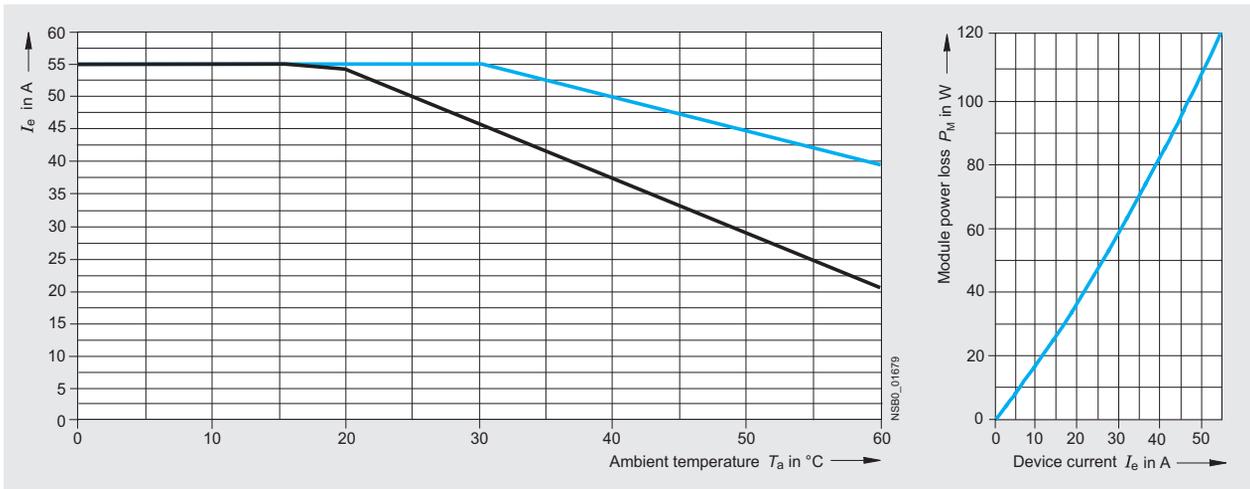
## Solid-State Contactors

### 3RF24 solid-state contactors, 3-phase

- 1
- 2
- 3
- 4
- 5
- 6
- 7



Type current 40 A (3RF24 40-.AB..)¹)



Type current 50 A (3RF24 50-.AB..)¹)

- $I_{max}$  Thermal limit current for individual mounting
- - -  $I_{max}$  Thermal limit current for side-by-side mounting
- $I_{IEC}$  Current acc. to IEC 947-4-3 for individual mounting
- - -  $I_{IEC}$  Current acc. to IEC 947-4-3 for side-by-side mounting

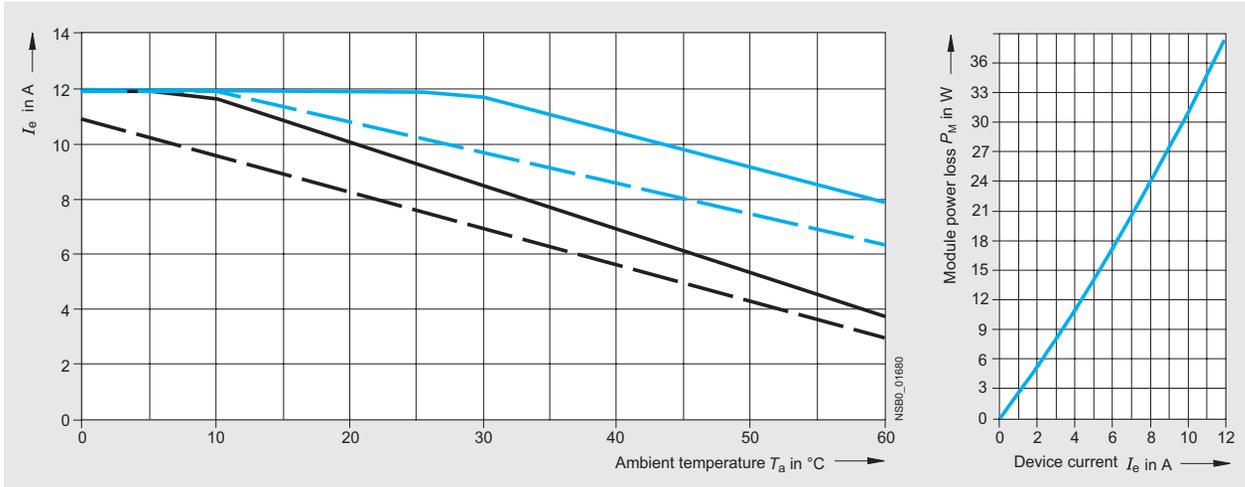
1) Identical current/temperature curves for stand-alone and side-by-side installation.

# Controls — Solid-State Switching Devices

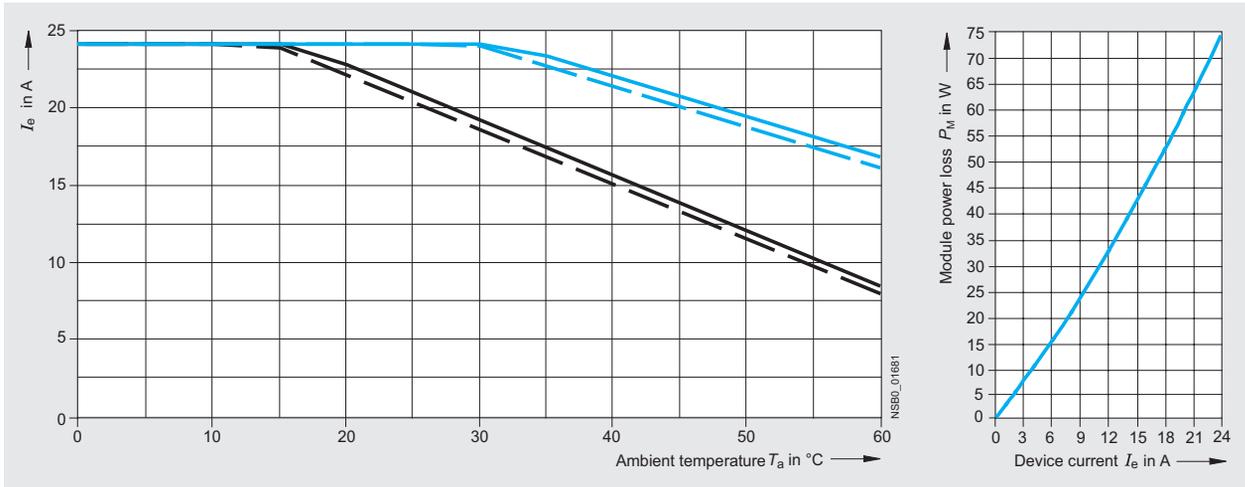
## Solid-State Contactors

### 3RF24 solid-state contactors, 3-phase

Derating curves, three-phase controlled

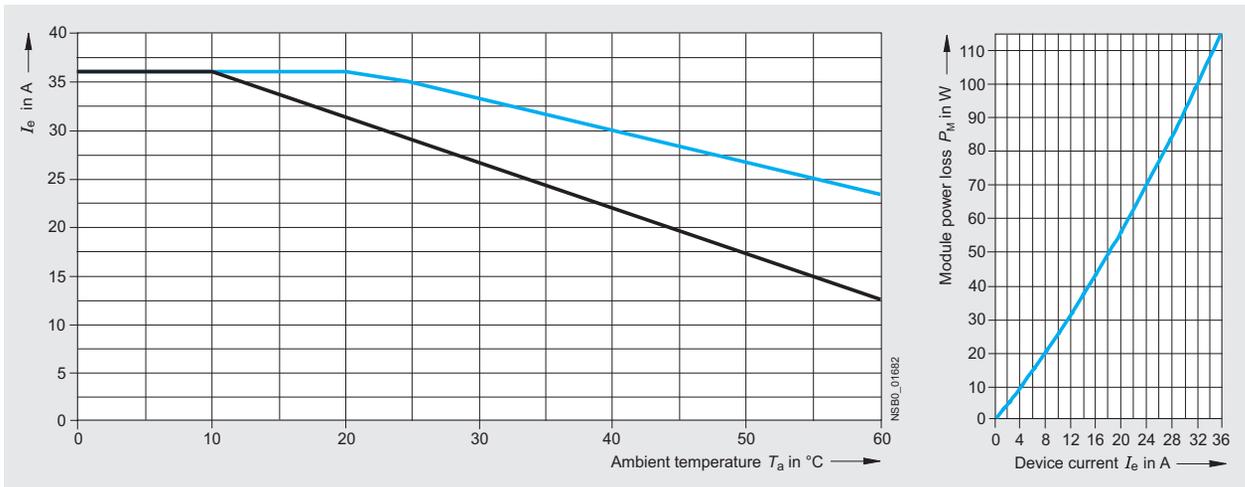


Type current 10.5 A (3RF24 10-.AC..)



Type current 20 A (3RF24 20-.AC..)

1) Identical current/temperature curves for stand-alone and side-by-side installation.



Type current 30 A (3RF24 30-.AC..)¹)

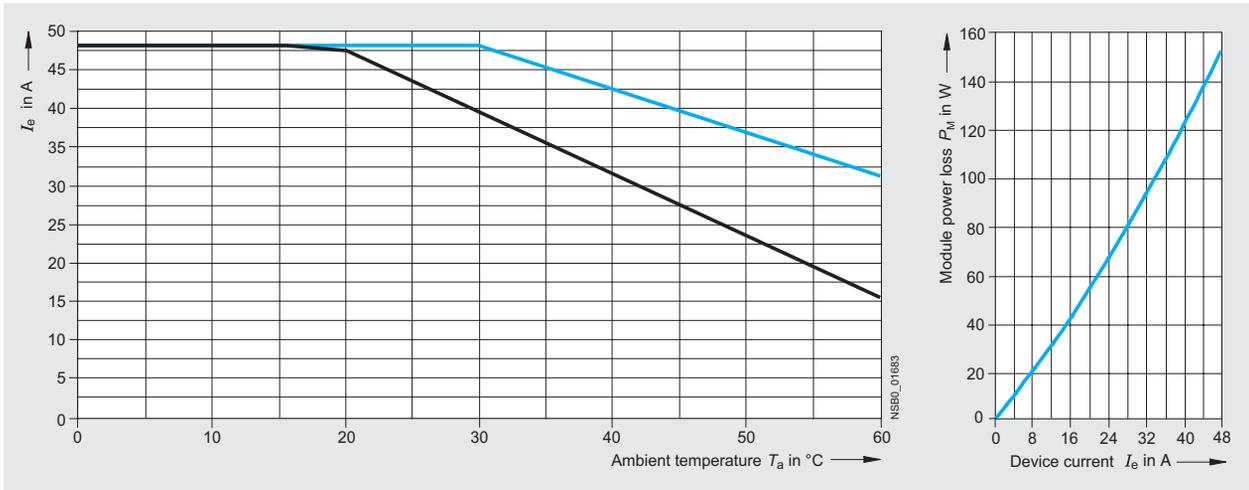
1) Identical current/temperature curves for stand-alone and side-by-side installation.

# Controls — Solid-State Switching Devices

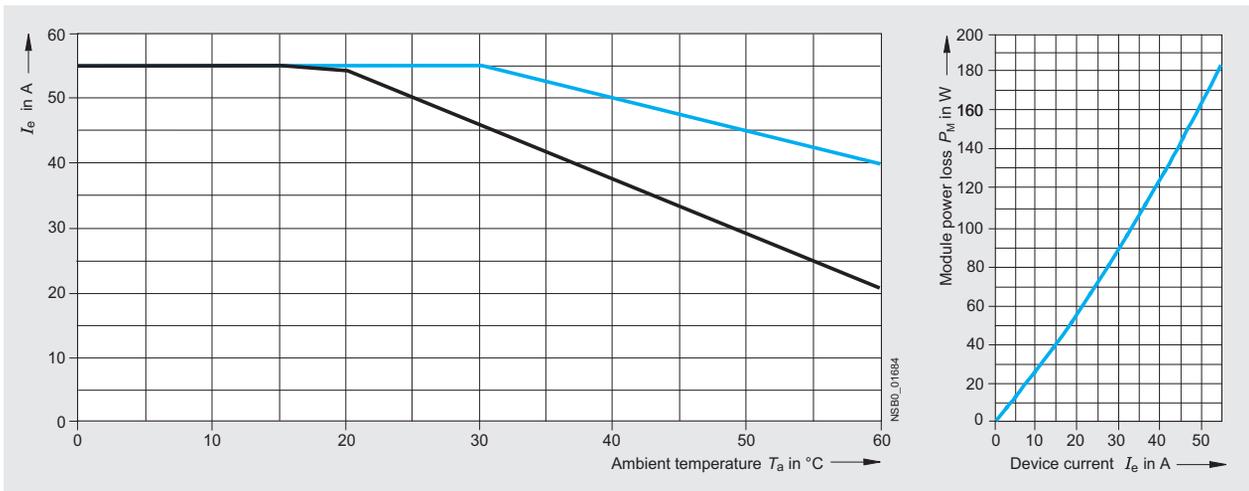
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### 3RF24 solid-state contactors, 3-phase

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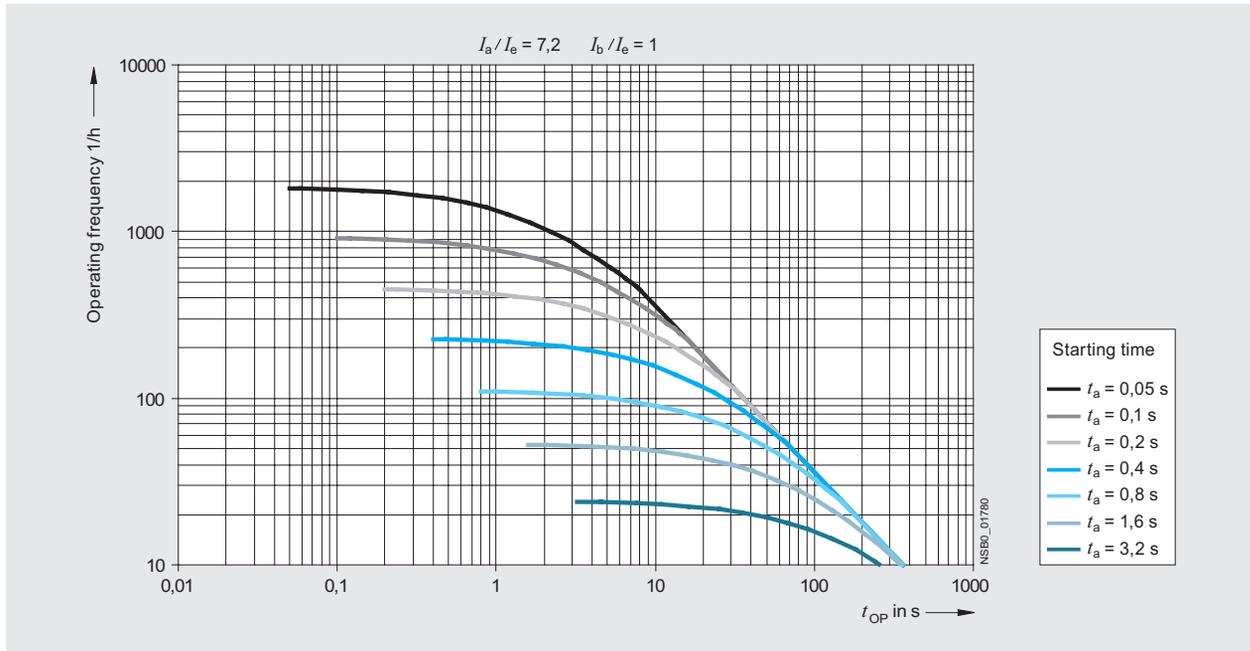
1) Identical current/temperature curves for stand-alone and side-by-side installation.

# Solid-State Switching Devices for Switching Motors

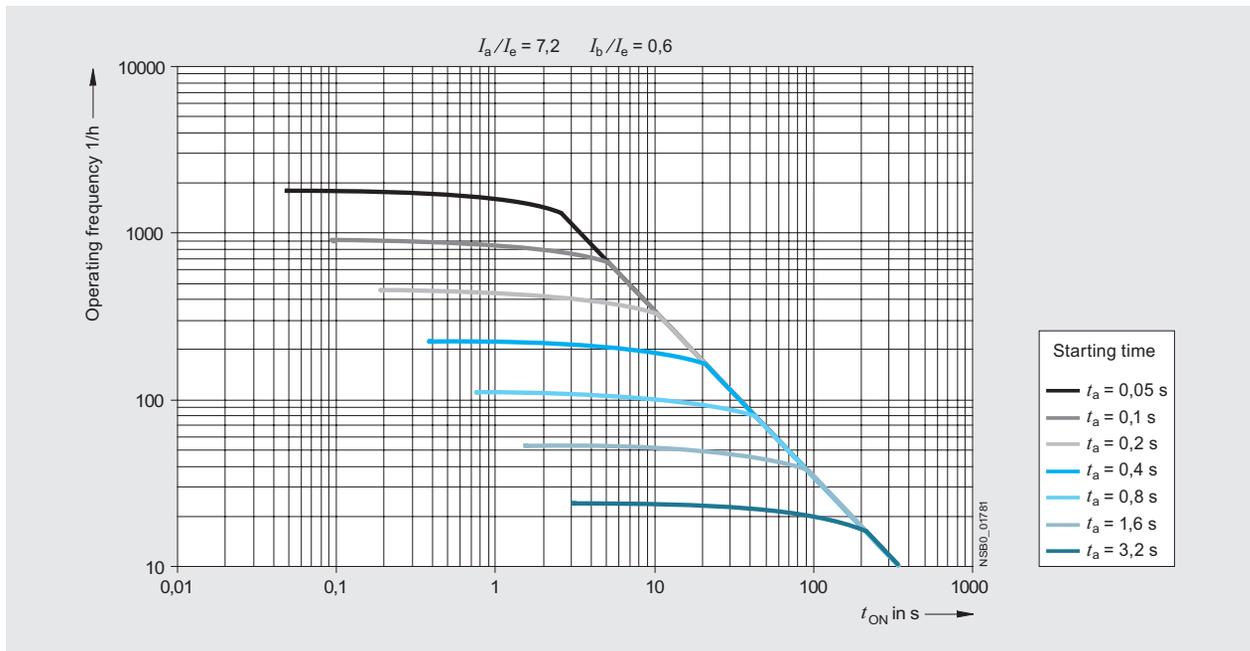
## Solid-State Contactors

### 3RF24 solid-state contactors, 3-phase

Maximum permissible switching frequency depending on the starting time  $t_a$  and the ON period  $t_{ED}$



For motors with a starting current of 4- to 7.2 times the rated current and with a full load



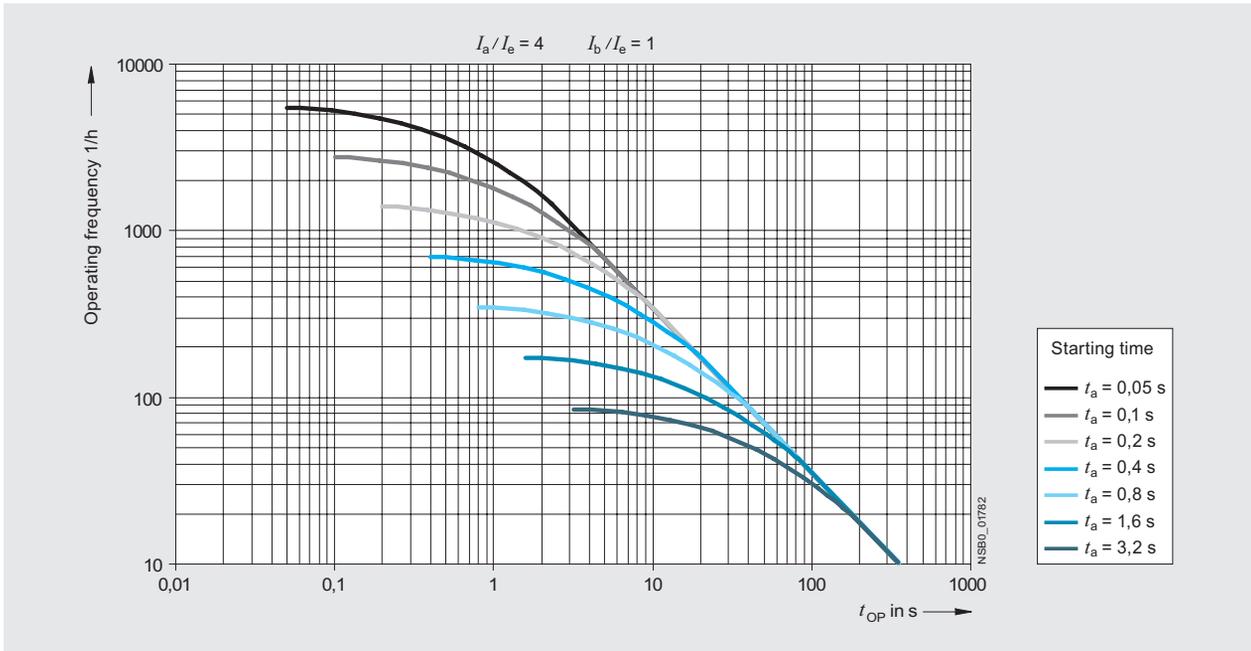
For motors with a starting current of 4- to 7.2 times the rated current and with a 60 % load

# Solid-State Switching Devices for Switching Motors

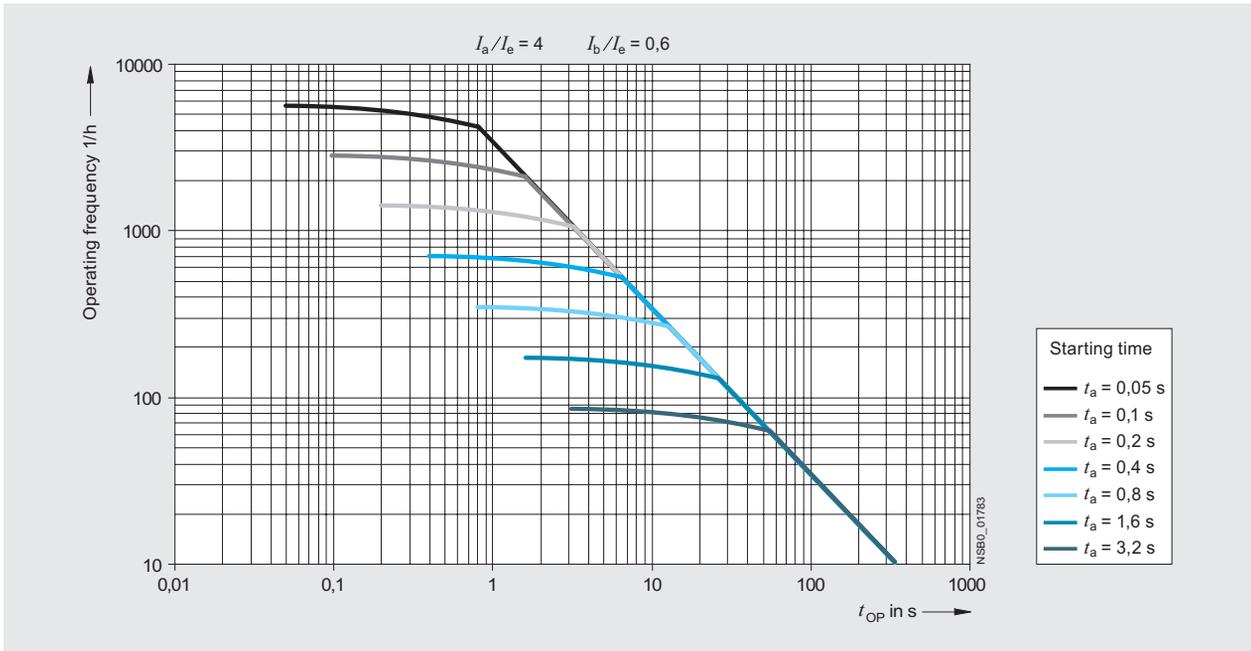
## Solid-State Contactors

### 3RF24 solid-state contactors, 3-phase

- 1
- 2
- 3
- 4
- 5
- 6
- 7



For motors with a starting current of up to 4 times the rated current and with a full load



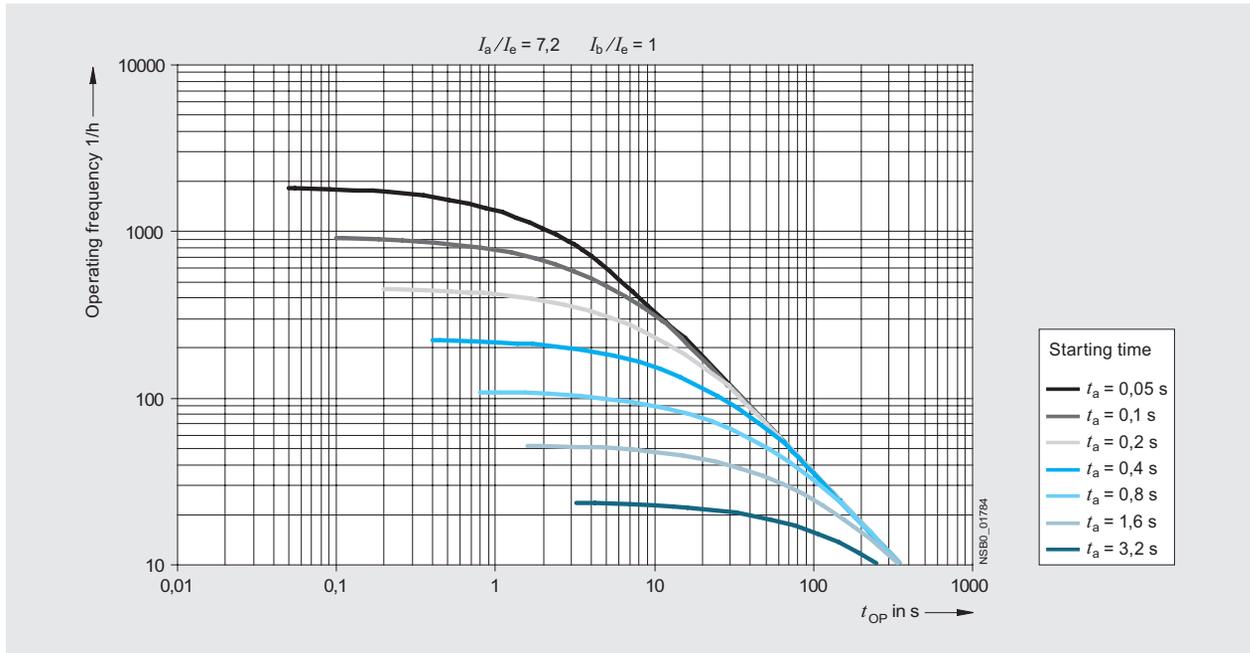
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# Solid-State Switching Devices for Switching Motors

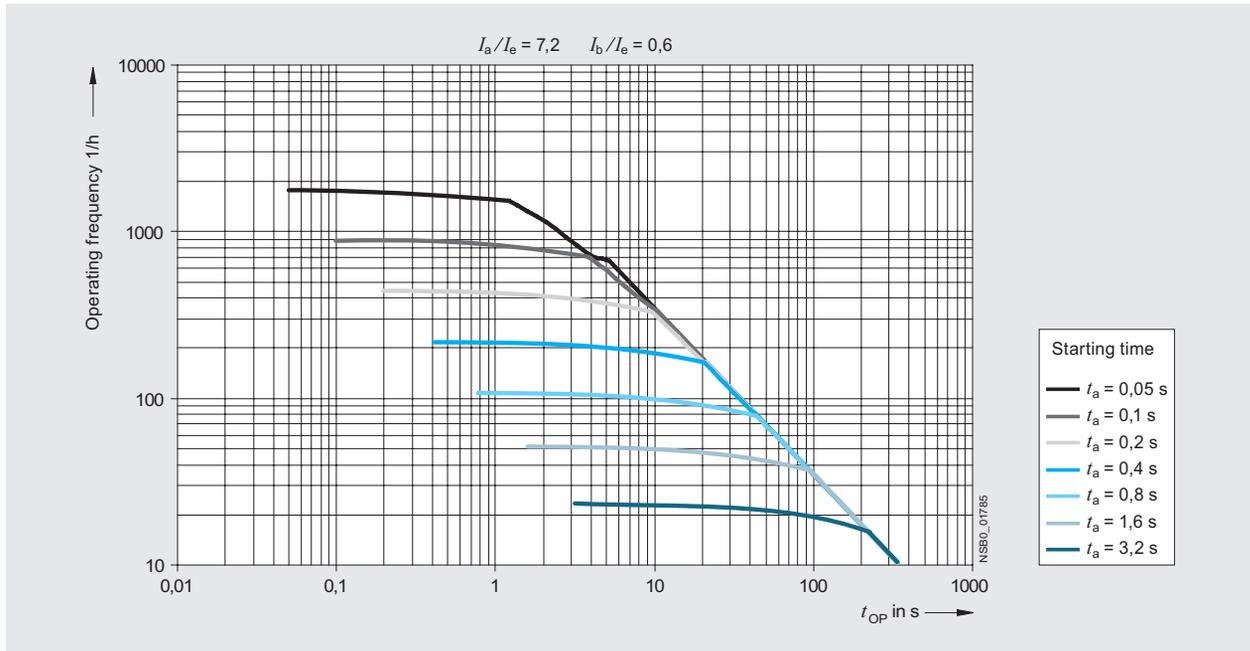
## Solid-State Contactors

3RF24 solid-state reversing contactors,  
3-phase

Maximum permissible switching frequency depending on the starting time  $t_a$  and the ON period  $t_{OP}$



For motors with a starting current of 4- to 7.2 times the rated current and with a full load

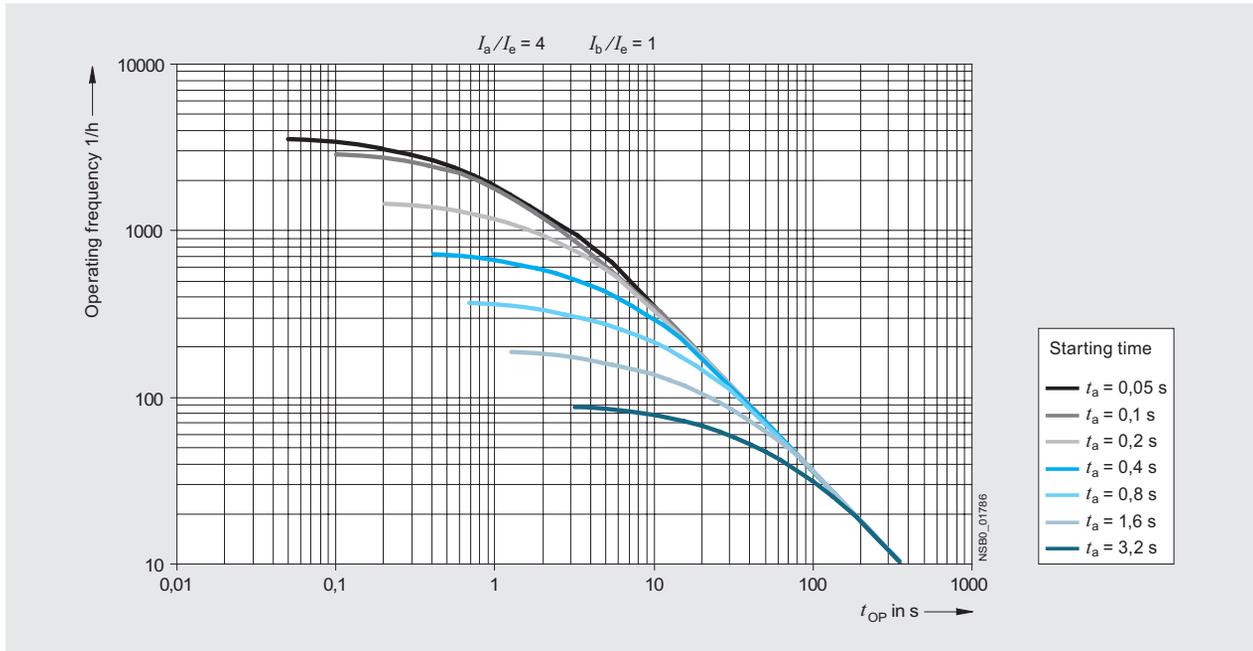


For motors with a starting current of 4- to 7.2 times the rated current and with a 60 % load

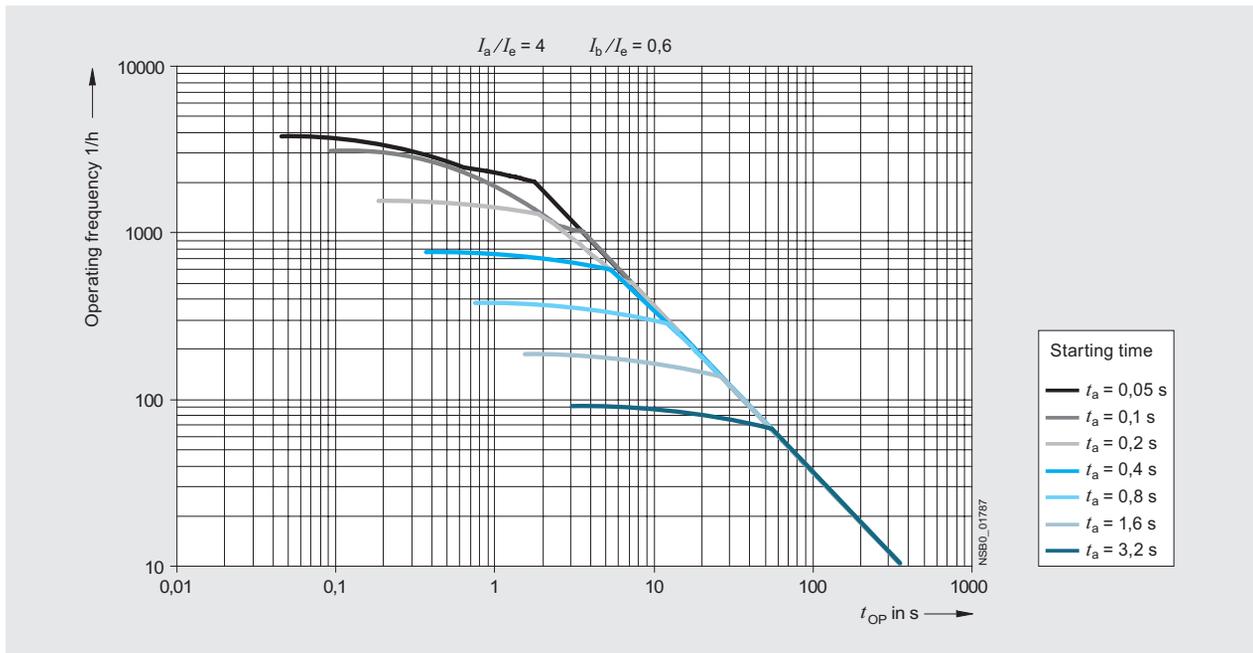
# Solid-State Switching Devices for Switching Motors

## Solid-State Contactors

3RF24 solid-state reversing contactors,  
3-phase



For motors with a starting current of up to 4 times the rated current and with a full load



For motors with a starting current of up to 4 times the rated current and with a 60 % load