SIEMENS

Data sheet 3RW4426-1BC35



SIRIUS soft starter Values at 575 V, 50 °C standard: 68 A, 50 hp Inside-delta: 118 A, 100 hp 400-600 V AC, 115 V AC Screw terminals !!! Phased-out product !!! Successor is SIRIUS 3RW5, Preferred successor type is >>3RW5526-1HA16<<

General technical data		
product brand name		SIRIUS
product feature		
 integrated bypass contact system 		Yes
• thyristors		Yes
product function		
 intrinsic device protection 		Yes
 motor overload protection 		Yes
 evaluation of thermistor motor protection 		Yes
external reset		Yes
 adjustable current limitation 		Yes
inside-delta circuit		Yes
product component motor brake output		Yes
insulation voltage rated value	V	690
degree of pollution		3, acc. to IEC 60947-4-2
reference code according to EN 61346-2		Q
reference code according to DIN 40719 extended		G
according to IEC 204-2 according to IEC 750		
Power Electronics		
product designation		Soft starter
operational current		
 at 40 °C rated value 	Α	77
 at 50 °C rated value 	Α	68
 at 60 °C rated value 	Α	59
operational current for 3-phase motors at inside-delta circuit		
 at 40 °C rated value 	Α	133
 at 50 °C rated value 	Α	118
 at 60 °C rated value 	Α	102
yielded mechanical performance for 3-phase motors		
• at 400 V		
 — at standard circuit at 40 °C rated value 	kW	37
 — at inside-delta circuit at 40 °C rated value 	kW	75
● at 500 V		
 at standard circuit at 40 °C rated value 	kW	45
 — at inside-delta circuit at 40 °C rated value 	kW	90
operating frequency rated value	Hz	50 60
relative negative tolerance of the operating frequency	%	-10
relative positive tolerance of the operating frequency	%	10
operating voltage at standard circuit rated value	V	400 600
relative negative tolerance of the operating voltage at standard circuit	%	-15

relative positive tolerance of the operating voltage at standard circuit	%	10
operating voltage at inside-delta circuit rated value	V	400 600
relative negative tolerance of the operating voltage at	%	-15
inside-delta circuit		
relative positive tolerance of the operating voltage at inside-delta circuit	%	10
minimum load [%]	%	8
adjustable motor current for motor overload protection minimum rated value	Α	15
continuous operating current [% of le] at 40 °C	%	115
power loss [W] at operational current at 40 °C during operation typical	W	45
Control circuit/ Control		
type of voltage of the control supply voltage		AC
control supply voltage frequency 1 rated value	Hz	50
control supply voltage frequency 2 rated value	Hz	60
relative negative tolerance of the control supply	%	-10
voltage frequency		
relative positive tolerance of the control supply voltage frequency	%	10
control supply voltage 1 at AC		
at 50 Hz rated value	V	115
• at 60 Hz rated value	V	115
relative negative tolerance of the control supply voltage at AC at 50 Hz	%	-15
relative positive tolerance of the control supply voltage at AC at 50 Hz	%	10
relative negative tolerance of the control supply voltage at AC at 60 Hz	%	-15
relative positive tolerance of the control supply	%	10
voltage at AC at 60 Hz		
voltage at AC at 60 Hz display version for fault signal		Display
		Display
display version for fault signal	mm	Display 170
display version for fault signal Mechanical data width height	mm mm	170 192
display version for fault signal Mechanical data width height depth		170 192 270
display version for fault signal Mechanical data width height depth fastening method	mm	170 192 270 screw fixing
display version for fault signal Mechanical data width height depth	mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and
display version for fault signal Mechanical data width height depth fastening method mounting position	mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with
display version for fault signal Mechanical data width height depth fastening method	mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards	mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum	mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm² 2.5 35 mm²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing • finely stranded without core end processing • stranded type of connectable conductor cross-sections for main contacts for box terminal using the back	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm² 2.5 35 mm² 4 50 mm²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing • finely stranded without core end processing • stranded type of connectable conductor cross-sections for	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm² 2.5 35 mm² 4 50 mm²

 finely stranded without core end processing 		10 50 mm²
stranded		10 70 mm²
type of connectable conductor cross-sections for main contacts for box terminal using both clamping points		
• solid		2x (2.5 16 mm²)
 finely stranded with core end processing 		2x (2.5 35 mm²)
 finely stranded without core end processing 		2x (4 35 mm²)
stranded		2x (4 50 mm²)
type of connectable conductor cross-sections at AWG cables for main contacts for box terminal		
 using the back clamping point 		10 2/0
 using the front clamping point 		10 2/0
 using both clamping points 		2x (10 1/0)
type of connectable conductor cross-sections for auxiliary contacts		
• solid		2x (0.5 2.5 mm²)
 finely stranded with core end processing 		2x (0.5 1.5 mm²)
type of connectable conductor cross-sections at AWG cables		
 for auxiliary contacts 		2x (20 14)
 for auxiliary contacts finely stranded with core end processing 		2x (20 16)
Ambient conditions		
installation altitude at height above sea level	m	5 000
environmental category		
 during transport according to IEC 60721 		2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m)

ambient tem	iperature
-------------	-----------

• during operation

• during storage

derating temperature

protection class IP on the front according to IEC 60529

• during storage according to IEC 60721

• during operation according to IEC 60721

touch protection on the front according to IEC 60529

1K6 (only occasional condensation), 1C2 (no salt mist), 1S2 (sand must not get inside the devices), 1M4

3K6 (no formation of ice, no condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6

°C 60

°C -25 ... +80

°C 40

IP20

finger-safe, for vertical contact from the front

Certificates/ approvals

General Product Approval



Confirmation









EMC

Declaration of Conformity

Test Certificates

Marine / Shipping





Type Test Certificates/Test Report

Special Test Certific-<u>ate</u>





Marine / Shipping









Confirmation

other

UL/CSA ratings

yielded mechanical performance [hp] for 3-phase AC motor

• at 460/480 V

- at standard circuit at 50 °C rated value

- at inside-delta circuit at 50 °C rated value

• at 575/600 V

- at standard circuit at 50 °C rated value

- at inside-delta circuit at 50 °C rated value

contact rating of auxiliary contacts according to UL

hp hp	50 75
hp hp	50 100 B300 / R300

Further information

Simulation Tool for Soft Starters (STS)

https://support.industry.siemens.com/cs/ww/en/view/101494917

Information on the packaging

https://support.industry.siemens.com/cs/ww/en/view/109813875

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RW4426-1BC35

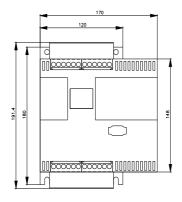
Cax online generator

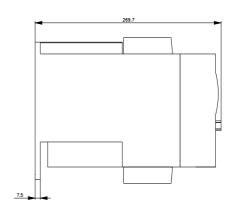
http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en&mlfb=3RW4426-1BC35

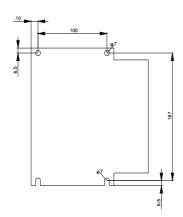
 ${\bf Service \& Support~(Manuals,~Certificates,~Characteristics,~FAQs,...)}$

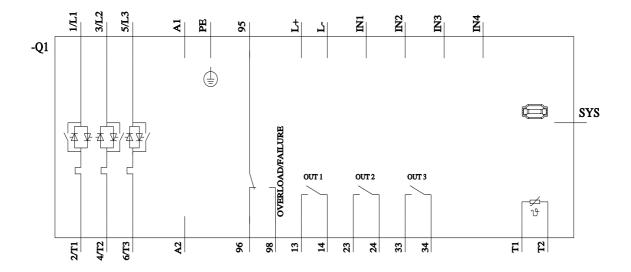
https://support.industry.siemens.com/cs/ww/en/ps/3RW4426-1BC35

Image database (product images, 2D dimension drawings, 3D models, device circuit diagrams, EPLAN macros, ...) http://www.automation.siemens.com/bilddb/cax_de.aspx?mlfb=3RW4426-1BC35&lang=en









last modified: 1/16/2022 🖸