SIEMENS

Data sheet

3RW4427-1BC44



SIRIUS soft starter Values at 400 V, 40 °C standard: 93 A, 45 kW Inside-delta: 161 A, 90 kW 200-460 V AC, 230 V AC Screw terminals !!! Phased-out product !!! Successor is SIRIUS 3RW5, Preferred successor type is >>3RW5527-1HA14<<

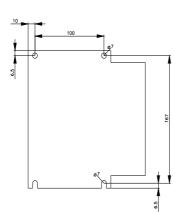
General technical data		
product brand name		SIRIUS
product feature		
 integrated bypass contact system 		Yes
thyristors		Yes
product function		
 intrinsic device protection 		Yes
 motor overload protection 		Yes
 evaluation of thermistor motor protection 		Yes
 external reset 		Yes
 adjustable current limitation 		Yes
 inside-delta circuit 		Yes
product component motor brake output		Yes
insulation voltage rated value	V	690
degree of pollution		3, acc. to IEC 60947-4-2
reference code according to EN 61346-2		Q
reference code according to DIN 40719 extended according to IEC 204-2 according to IEC 750		G
Power Electronics		
product designation		Soft starter
operational current		
 at 40 °C rated value 	А	93
 at 50 °C rated value 	А	82
 at 60 °C rated value 	А	72
operational current for 3-phase motors at inside-delta circuit		
• at 40 °C rated value	А	161
• at 50 °C rated value	А	142
 at 60 °C rated value 	А	125
yielded mechanical performance for 3-phase motors		
• at 230 V		
 — at standard circuit at 40 °C rated value 	kW	22
 — at inside-delta circuit at 40 °C rated value 	kW	45
• at 400 V		
 — at standard circuit at 40 °C rated value 	kW	45
 — at inside-delta circuit at 40 °C rated value 	kW	90
yielded mechanical performance [hp] for 3-phase AC motor at 200/208 V at standard circuit at 50 °C rated value	hp	25
operating frequency rated value	Hz	50 60
relative negative tolerance of the operating frequency	%	40
	70	-10

operating voltage at standard circuit rated value	V	200 460
relative negative tolerance of the operating voltage at	%	-15
standard circuit		
relative positive tolerance of the operating voltage at	%	10
standard circuit		
operating voltage at inside-delta circuit rated value	V	200 460
relative negative tolerance of the operating voltage at	%	-15
inside-delta circuit		
relative positive tolerance of the operating voltage at	%	10
inside-delta circuit		
minimum load [%]	%	8
adjustable motor current for motor overload	A	18
protection minimum rated value		
continuous operating current [% of le] at 40 °C	%	115
power loss [W] at operational current at 40 °C during	W	55
operation typical		
Control circuit/ Control		
type of voltage of the control supply voltage		AC
control supply voltage frequency 1 rated value	Hz	50
control supply voltage frequency 2 rated value	Hz	60
relative negative tolerance of the control supply	%	-10
voltage frequency		
relative positive tolerance of the control supply	%	10
voltage frequency		
control supply voltage 1 at AC		
 at 50 Hz rated value 	V	230
 at 60 Hz rated value 	V	230
relative negative tolerance of the control supply	%	-15
voltage at AC at 50 Hz		
relative positive tolerance of the control supply voltage at AC at 50 Hz	%	10
relative negative tolerance of the control supply voltage at AC at 60 Hz	%	-15
relative positive tolerance of the control supply	%	10
	, 0	
voltage at AC at 60 Hz		
voltage at AC at 60 Hz display version for fault signal		Display
-	_	Display
display version for fault signal Mechanical data	mm	
display version for fault signal Mechanical data width	mm	170
display version for fault signal Mechanical data width height	mm	170 192
display version for fault signal Mechanical data width height depth		170 192 270
display version for fault signal Mechanical data width height depth fastening method	mm	170 192 270 screw fixing
display version for fault signal Mechanical data width height depth	mm	170 192 270
display version for fault signal <u>Mechanical data</u> width height depth fastening method mounting position	mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and
display version for fault signal Mechanical data width height depth fastening method	mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and
display version for fault signal <u>Mechanical data</u> width height depth fastening method mounting position required spacing with side-by-side mounting	mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back
display version for fault signal <u>Mechanical data</u> width height depth fastening method mounting position required spacing with side-by-side mounting • upwards	mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards	mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of CO contacts for auxiliary contacts number of CO contacts for auxiliary contacts	mm mm mm mm	 170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of CO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm ²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm ² 2.5 35 mm ²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing • finely stranded without core end processing	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm ² 2.5 35 mm ² 4 50 mm ²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting outing point curved side hereit side outing point curved side outing point outing point	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm ² 2.5 35 mm ²
display version for fault signal Mechanical data width height depth fastening method mounting position required spacing with side-by-side mounting • upwards • at the side • downwards wire length maximum number of poles for main current circuit Connections/ Terminals type of electrical connection • for main current circuit • for auxiliary and control circuit number of NC contacts for auxiliary contacts number of NC contacts for auxiliary contacts number of NO contacts for auxiliary contacts number of CO contacts for auxiliary contacts type of connectable conductor cross-sections for main contacts for box terminal using the front clamping point • solid • finely stranded with core end processing • finely stranded without core end processing	mm mm mm mm	170 192 270 screw fixing with vertical mounting surface +/-90° rotatable, with vertical mounting surface +/- 22.5° tiltable to the front and back 100 5 75 500 3 box terminal screw-type terminals 0 3 1 2.5 16 mm ² 2.5 35 mm ² 4 50 mm ²

• solid		$0 = 40 \text{ mm}^2$
		2,5 16 mm²
 finely stranded with core end processing 		2.5 50 mm ²
 finely stranded without core end processing 		10 50 mm²
• stranded		10 70 mm²
type of connectable conductor cross-sections for main contacts for box terminal using both clamping points		
• solid		2x (2.5 16 mm²)
 finely stranded with core end processing 		2x (2.5 35 mm ²)
 finely stranded without core end processing 		2x (4 35 mm ²)
• stranded		2x (4 50 mm ²)
type of connectable conductor cross-sections at AWG cables for main contacts for box terminal		
 using the back clamping point 		10 2/0
 using the front clamping point 		10 2/0
 using both clamping points 		2x (10 1/0)
type of connectable conductor cross-sections for auxiliary contacts		
• solid		2x (0.5 2.5 mm ²)
 finely stranded with core end processing 		2x (0.5 1.5 mm²)
type of connectable conductor cross-sections at AWG cables		0. (00 44)
 for auxiliary contacts 		2x (20 14)
 for auxiliary contacts finely stranded with core end processing 		2x (20 16)
Ambient conditions		
	m	5 000
installation altitude at height above sea level environmental category	m	5 000
• during transport according to IEC 60721		2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m)
during transport according to IEC 60721 during storage according to IEC 60721		1K6 (only occasional condensation), 1C2 (no salt mist),
• during storage according to IEC 00721		1S2 (sand must not get inside the devices), 1M4
during operation according to IEC 60721		3K6 (no formation of ice, no condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6
ambient temperature		
 during operation 	°C	60
 during storage 	°C	-25 +80
derating temperature	°C	40
protection class IP on the front according to IEC 60529		IP20
touch protection on the front according to IEC 60529		
		finder-safe for vertical contact from the front
		finger-safe, for vertical contact from the front
Certificates/ approvals		
		finger-safe, for vertical contact from the front EMC
Certificates/ approvals General Product Approval		
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yielded mechanical performance [hp] for 3-phase AC		
motor		
• at 200/208 V		
 — at inside-delta circuit at 50 °C rated value 	hp	40
• at 220/230 V		
 — at standard circuit at 50 °C rated value 	hp	25
 — at inside-delta circuit at 50 °C rated value 	hp	50
● at 460/480 V		
— at standard circuit at 50 °C rated value	hp	60
 — at inside-delta circuit at 50 °C rated value 	hp	100
contact rating of auxiliary contacts according to UL		B300 / R300
urther information		
Simulation Tool for Soft Starters (STS)		
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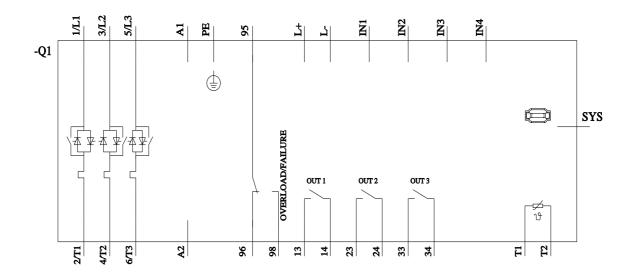


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