

Data sheet for SINAMICS G120C

Article No.: 6SL3210-1KE31-1UF1

Client order no. : Order no. : Offer no. : Remarks :





Figure similar

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	-20 %
Line frequency	47 63 Hz	
Rated current (LO)	96.00 A	
Rated current (HO)	85.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC 1)
Rated power (LO)	55.00 kW	60.00 hp
Rated power (HO)	45.00 kW	50.00 hp
Rated current (LO)	103.00 A	
Rated current (HO)	83.00 A	
Rated current (IN)	103.00 A	
Max. output current	165.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload	capability
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Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200~% base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications	
Power factor λ	0.90 0.95
Offset factor $\cos\phi$	0.99
Efficiency η	0.98
Sound pressure level (1m)	71 dB
Power loss	1,570.0 W
Filter class (integrated)	Unfiltered
Communication	

Communication	PROFINET, EtherNet/IP

Inputs / outputs	
Standard digital inputs	
Number	6
Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A
Analog / digital inputs	
Number	1 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0→1	4 V
1→0	1.6 V
Analog outputs	
Number	1 (Non-isolated output)
PTC/ KTY interface	

, KIT IIICITACC

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques	
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

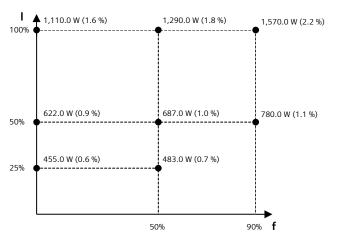


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Ambi	Ambient conditions		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.083 m³/s (2.931 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 40 °C (-4 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			
Max. operation	95 % RH, condensation not permitted		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	25.00 70.00 mm ² (AWG 4 AWG -1)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	25.00 70.00 mm ² (AWG 4 AWG -1)		
DC link (for braking resistor)			
Version	Screw-type terminals		
Conductor cross-section	25.00 70.00 mm ² (AWG 4 AWG -1)		
Line length, max.	10 m (32.81 ft)		
PE connection	Screw-type terminals		
Max. motor cable length			
Shielded	200 m (656.17 ft)		
Unshielded	300 m (984.25 ft)		

Converter losses to IEC61800-9-2*	
Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	47.0 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

Mechanical data

FSE

IP20 / UL open type

UL, cUL, CE, C-Tick (RCM)

EMC Directive 2004/108/EC, Low-

Voltage Directive 2006/95/EC

Degree of protection

Compliance with standards

Frame size

CE marking

^{*}converted values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 440V-480V

Net weight
 26.50 kg (58.42 lb)

 Dimensions

 Width
 275 mm (10.83 in)

 Height
 551 mm (21.69 in)

 Depth
 237 mm (9.33 in)

 Standards