Specification





# Variable speed drive, Altivar Machine ATV340, 18 kW, 400 V, 3 phases,

ATV340D18N4

#### Main

Range of product	Altivar Machine ATV340
product or component type	Variable speed drive
Product specific application	Machine
variant	Standard version
mounting mode	Cabinet mount
Communication port protocol	Modbus serial
Option card	Communication module, Profibus DP V1 Communication module, PROFINET Communication module, DeviceNet Communication module, CANopen Communication module, EtherCAT
Network number of phases	3 phases
Supply frequency	5060 Hz +/- 5 %
[Us] rated supply voltage	380480 V - 1510 %
Nominal output current	39.0 A
Motor power kW	22 kW for normal duty 18.5 kW for heavy duty
Motor power hp	30 hp for normal duty 25 hp for heavy duty
EMC filter	Class C3 EMC filter integrated
IP degree of protection	IP20

#### Complementary

Discrete input number	5	
Discrete input type	PTI programmable as pulse input: 030 kHz, 24 V DC (30 V) DI1DI5 safe torque off, 24 V DC (30 V), impedance: 3.5 kOhm programmable	
number of preset speeds	16 preset speeds	
Discrete output number	2.0	
Discrete output type	Programmable output DQ1, DQ2 30 V DC 100 mA	
Analogue input number	2	
Analogue input type	Al1 software-configurable current: 020 mA, impedance: 250 Ohm, resolution 12 bits Al1 software-configurable temperature probe or water level sensor Al1 software-configurable voltage: 010 V DC, impedance: 31.5 kOhm, resolution 12 bits Al2 software-configurable voltage: - 1010 V DC, impedance: 31.5 kOhm, resolution 12 bits	

Price is "List Price" and may be subject to a trade discount – check with your local distributor or retailer for actual price.

Analogue output number	1		
Analogue output type	Software-configurable voltage AQ1: 010 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1: 020 mA impedance 500 Ohm, resolution 10 bits		
Relay output number	2		
Output voltage	<= power supply voltage		
Relay output type	Relay outputs R1A Relay outputs R1C electrical durability 100000 cycles Relay outputs R2A Relay outputs R2C electrical durability 100000 cycles		
Maximum switching current	Relay output R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2C on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2C on inductive load, cos phi = 1: 5 A at 30 V DC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC		
Minimum switching current	Relay output R1B: 5 mA at 24 V DC Relay output R2C: 5 mA at 24 V DC		
Physical interface	2-wire RS 485		
Connector type	1 RJ45		
Method of access	Slave Modbus RTU		
Transmission rate	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s		
Transmission frame	RTU		
Number of addresses	1247		
Data format	8 bits, configurable odd, even or no parity		
Type of polarization	No impedance		
4 quadrant operation possible	True		
Asynchronous motor control profile	Optimized torque mode Variable torque standard Constant torque standard		
Synchronous motor control profile	Reluctance motor Permanent magnet motor		
Pollution degree	2 conforming to IEC 61800-5-1		
Maximum output frequency	0.599 kHz		
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.019999 s		
Motor slip compensation	Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law		
Switching frequency	216 kHz adjustable 416 kHz with derating factor		
Nominal switching frequency	4 kHz		
Braking to standstill	By DC injection		
Brake chopper integrated	True		

Line current	43.4 A at 380 V (normal duty)	
	35.0 A at 480 V (normal duty)	
	54.7 A at 380 V (heavy duty)	
	43.4 A at 480 V (heavy duty)	
Line current	54.7 A at 380 V without line choke (heavy duty)	
	43.4 A at 480 V without line choke (heavy duty)	
	49.9 A at 380 V with external line choke (normal duty)	
	40.2 A at 480 V with external line choke (normal duty)	
	54.5 A at 480 V with external line choke (heavy duty)	
	43.5 A at 380 V with external line choke (heavy duty)	
Maximum input current	54.7 A	
Maximum output voltage	480 V	
Apparent power	33.4 kVA at 480 V (normal duty)	
	36.1 kVA at 480 V (heavy duty)	
Maximum transient current	50.6 A during 60 s (normal duty)	
	59 A during 60 s (heavy duty)	
	62.1 A during 2 s (normal duty)	
	70 A during 2 s (heavy duty)	
Electrical connection	Committee description of the CO Committee of the CO Committee of the Co	
Electrical connection	Screw terminal, clamping capacity: 0.22.5 mm² for control	
	Screw terminal, clamping capacity: 1025 mm² for line side Screw terminal, clamping capacity: 1025 mm² for DC bus	
	Screw terminal, clamping capacity: 1025 mm² for motor	
Donate at the Boards		
Prospective line Isc	22 kA	
Base load current at high overload	39.0 A	
Base load current at low overload	46.0 A	
Power dissipation in W	Natural convection: 21 W at 380 V, switching frequency 4 kHz (heavy duty)	
·	Forced convection: 410 W at 380 V, switching frequency 4 kHz (heavy duty)	
	Natural convection: 23 W at 380 V, switching frequency 4 kHz (normal duty)	
	Forced convection: 464 W at 380 V, switching frequency 4 kHz (normal duty)	
Electrical connection	Control: screw terminal 0.22.5 mm²/AWG 24AWG 12	
	Line side: screw terminal 1025 mm²/AWG 8AWG 3	
	DC bus: screw terminal 1025 mm²/AWG 8AWG 3	
	Motor: screw terminal 625 mm²/AWG 8AWG 3	
With cafety function Safety		
With safety function Safely Limited Speed (SLS)	Motor: screw terminal 625 mm²/AWG 8AWG 3  True	
,		
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe	True	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position	True True	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)	True False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)	True  False  False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe	True  False  False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe programmable logic  With safety function Safe Speed	True  True  False  False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe programmable logic  With safety function Safe Speed Monitor (SSM)  With safety function Safe Stop 1	True  True  False  False  False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe programmable logic  With safety function Safe Speed Monitor (SSM)  With safety function Safe Stop 1 (SS1)	True  True  False  False  False  True	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe programmable logic  With safety function Safe Speed Monitor (SSM)  With safety function Safe Stop 1 (SS1)  With sft fct Safe Stop 2 (SS2)	True  True  False  False  True  False  False  False	
Limited Speed (SLS)  With safety function Safe brake management (SBC/SBT)  With safety function Safe Operating Stop (SOS)  With safety function Safe Position (SP)  With safety function Safe programmable logic  With safety function Safe Speed Monitor (SSM)  With safety function Safe Stop 1 (SS1)  With sft fct Safe Stop 2 (SS2)  With safety function Safe torque off (STO)  With safety function Safely	True  True  False  False  True  False  True  True	

Protection type	Thermal protection: motor Safe torque off: motor		
	Motor phase loss: motor		
	Thermal protection: drive		
	Safe torque off: drive		
	Overheating: drive Overcurrent: drive		
	Output overcurrent between motor phase and earth: drive		
	Output overcurrent between motor phases: drive		
	Short-circuit between motor phase and earth: drive		
	Short-circuit between motor phases: drive		
	Motor phase loss: drive		
	DC Bus overvoltage: drive		
	Line supply overvoltage: drive		
	Line supply undervoltage: drive		
	Input supply loss: drive		
	Exceeding limit speed: drive		
	Break on the control circuit: drive		
Width	180.0 mm		
Height	385.0 mm		
Depth	249.0 mm		
net weight	10.2 kg		
Continuous output current	46 A at 4 kHz for normal duty		
	39 A at 4 kHz for heavy duty		

#### **Environment**

Operating altitude	<= 3000 m with current derating above 1000m	
Operating position	Vertical +/- 10 degree	
Product certifications	UL CSA TÜV EAC CTick	
marking	CE	
Standards	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C	
Assembly style	With heat sink	
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6	
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3	
Maximum acceleration under shock impact (during operation)	70 m/s² at 22 ms	
Maximum acceleration under vibrational stress (during operation)	5 m/s² at 9200 Hz	
Maximum deflection under vibratory load (during operation)	1.5 mm at 29 Hz	
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3	
Volume of cooling air	128.0 m3/h	
Type of cooling	Forced convection	
Overvoltage category	Class III	

Regulation loop	Adjustable PID regulator
Noise level	56.7 dB
Pollution degree	2
Ambient air transport temperature	-4070 °C
Ambient air temperature for operation	-1550 °C without derating (vertical position) 5060 °C with derating factor (vertical position)
Ambient air temperature for storage	-4070 °C
Isolation	Between power and control terminals

# **Packing Units**

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	34.000 cm
Package 1 Width	30.500 cm
Package 1 Length	56.000 cm
Package 1 Weight	11.900 kg
Unit Type of Package 2	P06
Number of Units in Package 2	2
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	36.800 kg

# Sustainability Green Premium

**Green Premium**<sup>TM</sup> **label** is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Learn more about Green Premium >

Guide to assess a product's sustainability >





Transparency RoHS/REACh

#### Resource performance



Upgraded Components Available

#### Well-being performance



Mercury Free



Rohs Exemption Information

Yes

#### **Certifications & Standards**

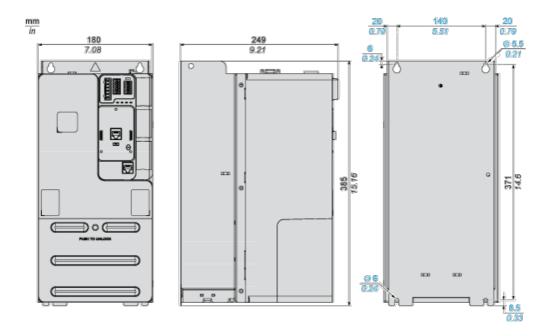
Reach Regulation	Pro-active compliance (Product out of EU RoHS legal scope)	
Eu Rohs Directive		
China Rohs Regulation	China RoHS declaration	
Environmental Disclosure	Product Environmental Profile	
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	
Circularity Profile	End of Life Information	

Jul 2, 2024

#### **Dimensions Drawings**

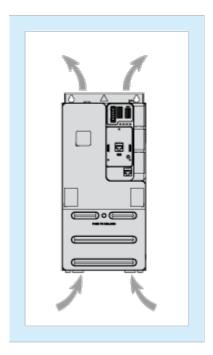
#### **Dimensions**

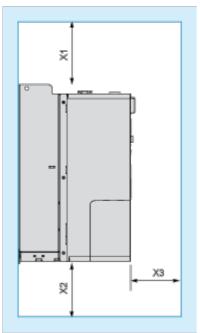
#### Views: Front - Left - Rear



#### Mounting and Clearance

#### Clearance





Dimensions in mm

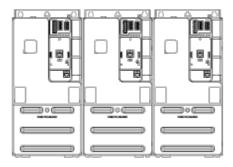
X1	X2	X3
≥ 100	≥ 100	≥ 60

#### Dimensions in in.

X1	X2	Х3
≥ 3.94	≥ 3.94	≥ <sub>2.36</sub>

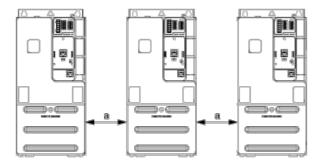
#### **Mounting Types**

#### Mounting Type A: Side by Side IP20



Possible, at ambient temperature ≤ 50 °C (122 °F)

#### Mounting Type B: Individual IP20



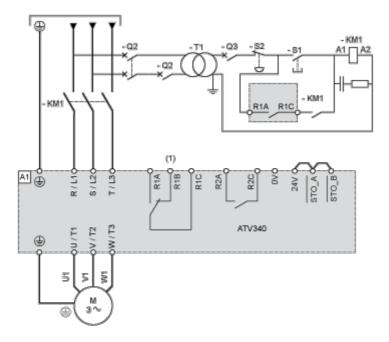
a 50 mm (1.97 in.) from 50...60°C, no restriction below 50°C

#### Connections and Schema

#### **Connections and Schema**

# Three-phase Power Supply with Upstream Breaking via Line Contactor Without Safety Function STO

Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



(1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

A1: Drive

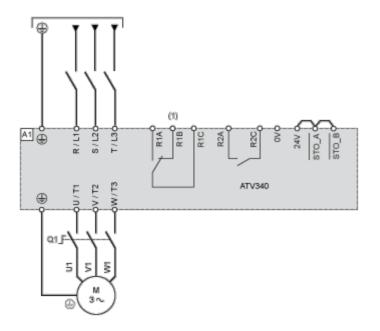
KM1 : Line ContactorQ2, Q3 : Circuit breakers

S1: PushbuttonS2: Emergency stop

T1: Transformer for control part

Three-phase Power Supply With Downstream Breaking via Switch Disconnector

#### ATV340D18N4

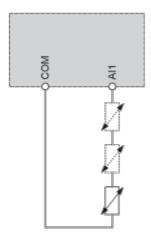


(1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

A1: Drive

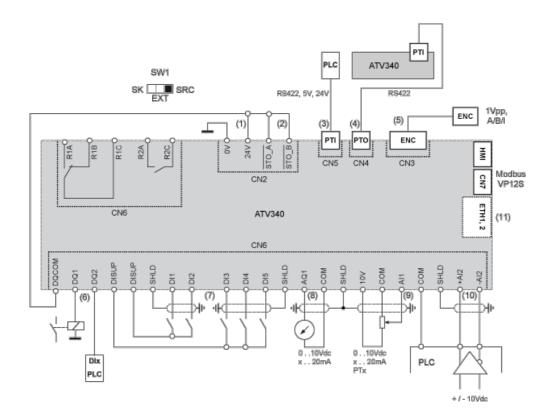
Q1: Switch disconnector

#### **Sensor Connection**



It is possible to connect either 1 or 3 sensors on terminals Al1.

#### **Control Block Wiring Diagram**

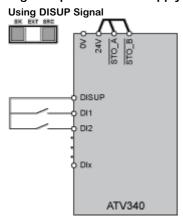


- (1) 24V supply (STO)
- (2) STO Safe Torque Off
- (3) PTI Pulse Train In
- (4) PTO Pulse Train Out
- (5) Motor Encoder connection
- (6) Digital outputs
- (7) Digital inputs
- (8) Analog output
- (9) Analog input
- (10) Differential Analog Input
- (11) Ethernet port (only on Ethernet drive version)

SW1: Sink/Source switch
R1A, R1B, R1C: Fault relay
R2A, R2C: Sequence relay

#### **Digital Inputs Wiring**

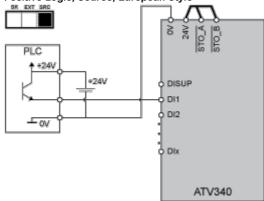
#### **Digital Inputs: Internal Supply**



In SRC position DISUP outputs 24 V. In SK position DISUP is connected to 0 V.

#### **Digital Inputs: External Supply**

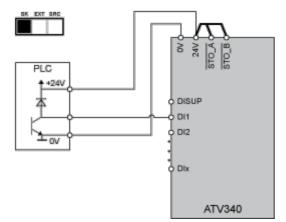
#### Positive Logic, Source, European Style



# Negative Logic, Sink, Asian Style PLC +24V DISUP DIX ATV340

Digital Inputs: Internal supply Negative Logic, Sink, Asian Style

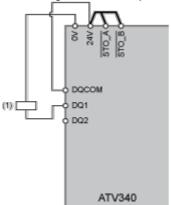
#### ATV340D18N4



#### **Digital Outputs Wiring**

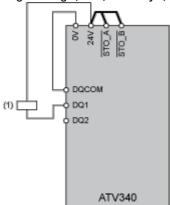
#### **Digital Outputs: Internal Supply**

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

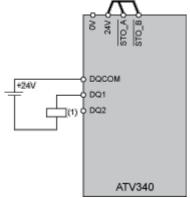
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

#### **Digital Outputs: External Supply**

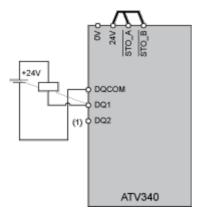
Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

Negative Logic, Sink, Asian Style, DQCOM to 0V

# ATV340D18N4

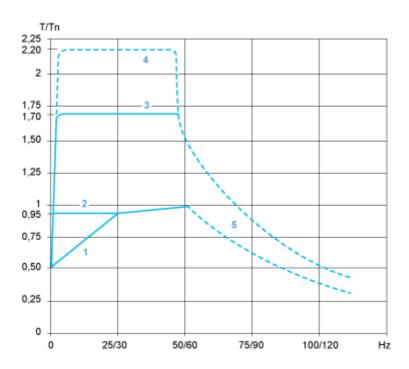


(1) Relay or valve

#### ATV340D18N4

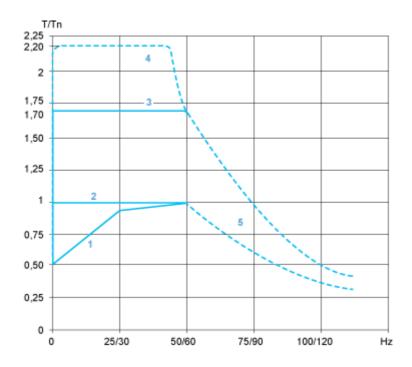
#### Performance Curves

#### **Open Loop Applications**



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power

#### **Closed Loop Applications**



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power