BMH0702P02F2A





Main

Product or component type	Servo motor				
Device short name	вмн				
Maximum mechanical speed	8000 rpm				
Continuous stall torque	22.12 lbf.in (2.5 N.m) for LXM32.D12N4 3 A at 400 V three phase 22.12 lbf.in (2.5 N.m) for LXM32.D12N4 3 A at 480 V three phase				
Peak stall torque	65.49 lbf.in (7.4 N.m) for LXM32.D12N4 3 A at 400 V three phase 65.49 lbf.in (7.4 N.m) for LXM32.D12N4 3 A at 480 V three phase				
Nominal output power	700 W LXM32.D12N4 3 A at 400 V three phase 700 W LXM32.D12N4 3 A at 480 V three phase				
Nominal torque	19.47 lbf.in (2.2 N.m) for LXM32.D12N4 3 A at 400 V three phase 19.47 lbf.in (2.2 N.m) for LXM32.D12N4 3 A at 480 V three phase				
Nominal speed	3000 rpm for LXM32.D12N4 3 A at 400 V three phase 3000 rpm for LXM32.D12N4 3 A at 480 V three phase				
Product compatibility	LXM32.D12N4 at 400480 V three phase				
Shaft end	Smooth shaft				
IP degree of protection	IP54 (standard)				
Speed feedback resolution	131072 points/turn x 4096 turns				
Holding brake	With				
Mounting support	International standard flange				
Electrical connection	Rotatable right-angled connectors				

Complementary

[Us] rated supply voltage	
Continuous stall current Continuous power 1.51 W Maximum current Irms 9.7 A for LXM32.D12N4 Maximum permanent current 9.68 A Second shaft Without second shaft end Shaft diameter 0.43 in (11 mm) Shaft length 0.91 in (23 mm) Feedback type Multiturn SinCos Hiperface Holding torque 26.55 lbf.in (3 N.m) (holding brake) Motor flange size 2.76 in (70 mm) Number of motor stacks 2 Torque constant 0.84 N.m/A at 248 °F (120 °C) Back emf constant 54.08 V/krpm at 248 °F (120 °C) Number of motor poles 10 Rotor inertia 1.24 kg.cm²	
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0.001 (0.000)	
Stator resistance 3.8 Ohm at 68 °F (20 °C)	
Stator inductance 12.2 mH at 68 °F (20 °C)	

Stator electrical time constant	3.2 ms at 68 °F (20 °C)
Maximum radial force Fr	390 N at 6000 rpm 410 N at 5000 rpm 450 N at 4000 rpm 490 N at 3000 rpm 560 N at 2000 rpm 710 N at 1000 rpm
Maximum axial force Fa	0.2 x Fr
Brake pull-in power	7 W
Type of cooling	Natural convection
Length	7.6 in (193 mm)
Centring collar diameter	2.36 in (60 mm)
Centring collar depth	0.1 in (2.5 mm)
Number of mounting holes	4
Mounting holes diameter	0.22 in (5.5 mm)
Circle diameter of the mounting holes	3.23 in (82 mm)
Product weight	7.28 lb(US) (3.3 kg)

Environment

Offer Sustainability

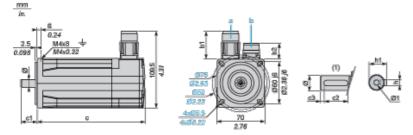
Green Premium product	Green Premium product			
Compliant - since 0936 - Schneider Electric declaration of conformity	Compliant - since 0936 - Schneider Electric declaration of conformity			
Reference not containing SVHC above the threshold	Reference not containing SVHC above the threshold			
Available	Available			
Need no specific recycling operations	Need no specific recycling operations			

Contractual warranty

Warranty period	18 months	
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Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)

Dimensions in mm

	traight Rotatable angled connectors		c (without brake)	c (with brake)	c1	c2	с3	h	h1	Ø	Ø1 for screws	
b1	b2	b1	b2									
39.5	25.5	39.5	39.5	154	193	23	18	2.5	4 h9	12.5 ⁺⁰ _{-0.13}	11 k6	M4 x 14

Dimensions in in.

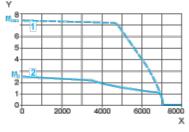


Strai	_	ang	table gled ectors	c (without brake)	c (with brake)	c 1	c2	с3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
1.55	1	1.55	1.55	6.06	7.59	0.90	0.70	0.09	0.16 h9	0.49 ⁺⁰ 0.0051	0.43 k6	M4 x 0.55

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D12N4 servo drive



X Speed in rpm

Y Torque in Nm

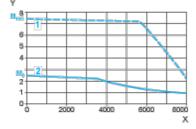
1 Peak torque

2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D12N4 servo drive



X Speed in rpm

Y Torque in Nm

1 Peak torque

2 Continuous torque