# **BMH1002P02A2A**





#### Main

Product or component type	Servo motor
Device short name	ВМН
Maximum mechanical speed	6000 rpm
Continuous stall torque	54.87 lbf.in (6.2 N.m) for LXM32.D18N4 6 A at 400 V three phase 54.87 lbf.in (6.2 N.m) for LXM32.D18N4 6 A at 480 V three phase
Peak stall torque	162.83 lbf.in (18.4 N.m) for LXM32.D18N4 6 A at 400 V three phase 162.83 lbf.in (18.4 N.m) for LXM32.D18N4 6 A at 480 V three phase
Nominal output power	1600 W for LXM32.D18N4 6 A at 400 V three phase 1600 W for LXM32.D18N4 6 A at 480 V three phase
Nominal torque	34.51 lbf.in (3.9 N.m) for LXM32.D18N4 6 A at 400 V three phase 34.51 lbf.in (3.9 N.m) for LXM32.D18N4 6 A at 480 V three phase
Nominal speed	4000 rpm for LXM32.D18N4 6 A at 400 V three phase 4000 rpm for LXM32.D18N4 6 A at 480 V three phase
Product compatibility	LXM32.D18N4 at 400480 V three phase
Shaft end	Smooth shaft
IP degree of protection	IP54 (standard)
Speed feedback resolution	131072 points/turn x 4096 turns
Holding brake	Without
Mounting support	International standard flange
Electrical connection	Rotatable right-angled connectors

### Complementary

Range compatibility	Lexium 32	
[Us] rated supply voltage	480 V	
Phase	Three phase	
Continuous stall current	5.04 A	
Continuous power	2.36 W	
Maximum current Irms	18 A for LXM32.D18N4	
Maximum permanent current	18.23 A	
Second shaft	Without second shaft end	
Shaft diameter	0.75 in (19 mm)	
Shaft length	1.57 in (40 mm)	
Feedback type	Multiturn SinCos Hiperface	
Motor flange size	3.94 in (100 mm)	
Number of motor stacks	2	
Torque constant	1.2 N.m/A at 248 °F (120 °C)	
Back emf constant	77 V/krpm at 248 °F (120 °C)	
Number of motor poles	10	
Rotor inertia	6.28 kg.cm <sup>2</sup>	
Stator resistance	1.51 Ohm at 68 °F (20 °C)	
Stator inductance	7.5 mH at 68 °F (20 °C)	

Stator electrical time constant	5 ms at 68 °F (20 °C)		
Maximum radial force Fr	620 N at 4000 rpm 690 N at 3000 rpm 790 N at 2000 rpm 990 N at 1000 rpm 580 N at 5000 rpm		
Maximum axial force Fa	0.2 x Fr		
Type of cooling	Natural convection		
Length	6.32 in (160.6 mm)		
Centring collar diameter	3.74 in (95 mm)		
Centring collar depth	0.14 in (3.5 mm)		
Number of mounting holes	4		
Mounting holes diameter	0.35 in (9 mm)		
Circle diameter of the mounting holes	4.53 in (115 mm)		
Product weight	10.85 lb(US) (4.92 kg)		

#### **Environment**

# Offer Sustainability

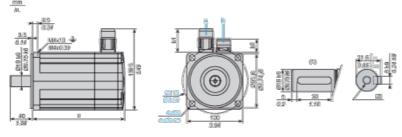
Green Premium product	Green Premium product
Compliant - since 0936 - Schneider Electric declaration of conformity	Compliant - since 0936 - Schneider Electric declaration of conformity
Reference not containing SVHC above the threshold	Reference not containing SVHC above the threshold
Available	Available
Need no specific recycling operations	Need no specific recycling operations

### Contractual warranty

Warranty period	18 months	
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### **Servo Motors Dimensions**

#### **Example with Straight Connectors**



- a: Power supply for servo motor brake
- **b:** Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)
- (2) For screw M6 x 21 mm/M6 x 0.83 in.

Dimensions in mm

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)
b1	b2	b1	b2		
39.5	25.5	39.5	39.5	160	202

Dimensions in in.

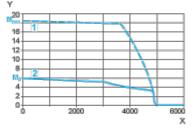
Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)
b1	b2	b1	b2		
1.55	1.00	1.55	1.55	6.29	7.95



# 400 V 3-Phase Supply Voltage

#### Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive

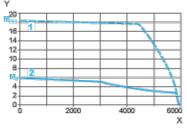


- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque

# 480 V 3-Phase Supply Voltage

### Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque