

BMH1002P07A1A

servo motor BMH - 6.2 Nm - 6000 rpm -
untapped shaft - without brake - IP54



Product availability: Non-Stock - Not normally stocked in distribution facility



Main

Product or component type	Servo motor
Device short name	BMH
Maximum mechanical speed	6000 rpm
Continuous stall torque	54.87 Lbf.In (6.2 N.m) LXM32.D18N4 6 A, 400 V, three phase 54.87 lbf.in (6.2 N.m) LXM32.D18N4 6 A, 480 V, three phase
Peak stall torque	162.85 Lbf.In (18.4 N.m) LXM32.D18N4 6 A, 400 V, three phase 162.85 lbf.in (18.4 N.m) LXM32.D18N4 6 A, 480 V, three phase
Nominal output power	1600 W LXM32.D18N4 6 A, 400 V, three phase 1600 W LXM32.D18N4 6 A, 480 V, three phase
Nominal torque	34.52 Lbf.In (3.9 N.m) LXM32.D18N4 6 A, 400 V, three phase 34.52 lbf.in (3.9 N.m) LXM32.D18N4 6 A, 480 V, three phase
Nominal speed	4000 rpm LXM32.D18N4 6 A, 400 V, three phase 4000 rpm LXM32.D18N4 6 A, 480 V, three phase
Product compatibility	LXM32.D18N4 400...480 V three phase
Shaft end	Smooth shaft
IP degree of protection	IP54 standard
Speed feedback resolution	32768 points/turn x 4096 turns
Holding brake	Without
Mounting support	International standard flange
Electrical connection	Straight connectors

Complementary

Range compatibility	Lexium 32
[Us] rated supply voltage	480 V
Phase	Three phase
Continuous stall current	5.04 A
Continuous power	2.36 W
Maximum current Irms	18 A LXM32.D18N4
Maximum permanent current	18.23 A
Second shaft	Without second shaft end
Shaft diameter	0.75 in (19 mm)
Shaft length	1.57 in (40 mm)
Feedback type	Multiturn SinCos Hiperface
Motor flange size	3.94 in (100 mm)
Number of motor stacks	2
Torque constant	1.2 N.m/A 248 °F (120 °C)
Back emf constant	77 V/krpm 248 °F (120 °C)
Number of motor poles	10
Rotor inertia	6.28 kg.cm ²
Stator resistance	1.51 Ohm 68 °F (20 °C)
Stator inductance	7.5 mH 68 °F (20 °C)

Stator electrical time constant	5 ms 68 °F (20 °C)
Maximum radial force Fr	990 N 1000 rpm 790 N 2000 rpm 690 N 3000 rpm 620 N 4000 rpm 580 N 5000 rpm
Maximum axial force Fa	0.2 x Fr
Type of cooling	Natural convection
Length	6.32 in (160.6 mm)
Centring collar diameter	3.74 in (95 mm)
Centring collar depth	0.14 in (3.5 mm)
Number of mounting holes	4
Mounting holes diameter	0.35 in (9 mm)
Circle diameter of the mounting holes	4.53 in (115 mm)
Net weight	10.85 lb(US) (4.92 kg)

Ordering and shipping details

Category	18282 - LEXIUM 32 MOTORS
Discount Schedule	PC53
GTIN	03606485196183
Package weight(Lbs)	5.21 kg (11.48 lb(US))
Returnability	No
Country of origin	DE

Offer Sustainability

Sustainable offer status	Green Premium product
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds which is known to the State of California to cause Carcinogen & Reproductive harm. For more information go to www.p65warnings.ca.gov
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS Declaration
Environmental Disclosure	Product Environmental Profile
Circularity Profile	No need of specific recycling operations
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins.

Contractual warranty

Warranty	18 months
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Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)
- (2) For screw M6 x 21 mm/M6 x 0.83 in.

Dimensions in mm

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)
b1	b2	b1	b2		
39.5	25.5	39.5	39.5	160	202

Dimensions in in.

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)
b1	b2	b1	b2		
1.55	1.00	1.55	1.55	6.29	7.95

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
Y Torque in Nm
1 Peak torque
2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
Y Torque in Nm
1 Peak torque
2 Continuous torque